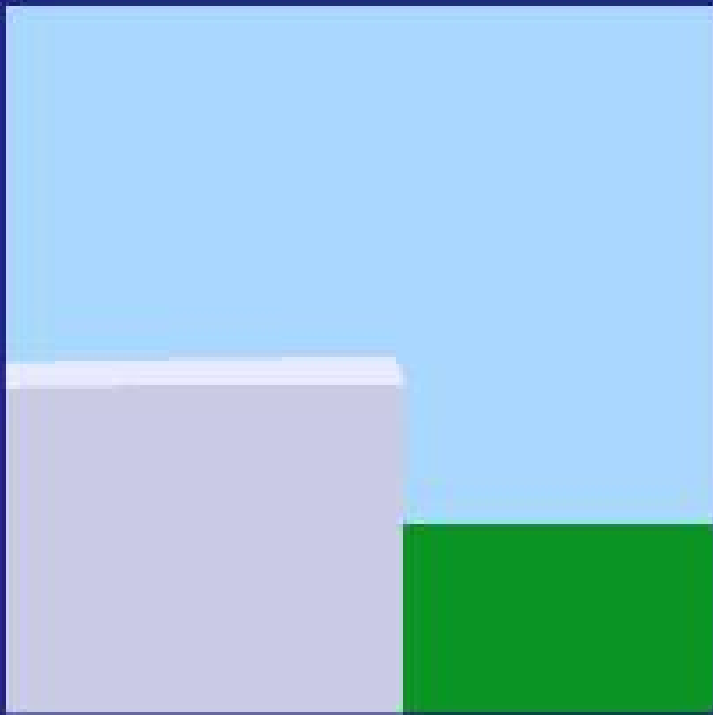


CMSC 435/634

Texture

Texturing Adds Richness



Texture Mapping

Mapping a function onto a surface

Function can be

- 1D, 2D or 3D
- Sampled (i.e. an image) or a mathematical function

Mapped Parameters

- Surface color (Catmull 74)
- Specular reflection (Blinn and Newell 76)
- Normal vector perturbation (Blinn 78)
- Specularity (Blinn 78)
- Transparency (Gardner 85)
- Diffuse Reflection (Miller and Hoffman 84)
- Shadows, displacements, etc (Cook 84)
- Local coord system (Kajiya 85)

Map Indices

Surface parameters

- Position
- Surface parameterization
- Manually defined *texture coordinates*

Ray direction

- reflection/environment mapping

Surface normal direction

- diffuse reflection mapping
- transparency/refraction mapping

Key Challenges

Mapping function determination

Resolution issues

Texture design/capture

Mapping Functions

Standard projecting functions

- planar
- cylindrical
- spherical

Mechanism

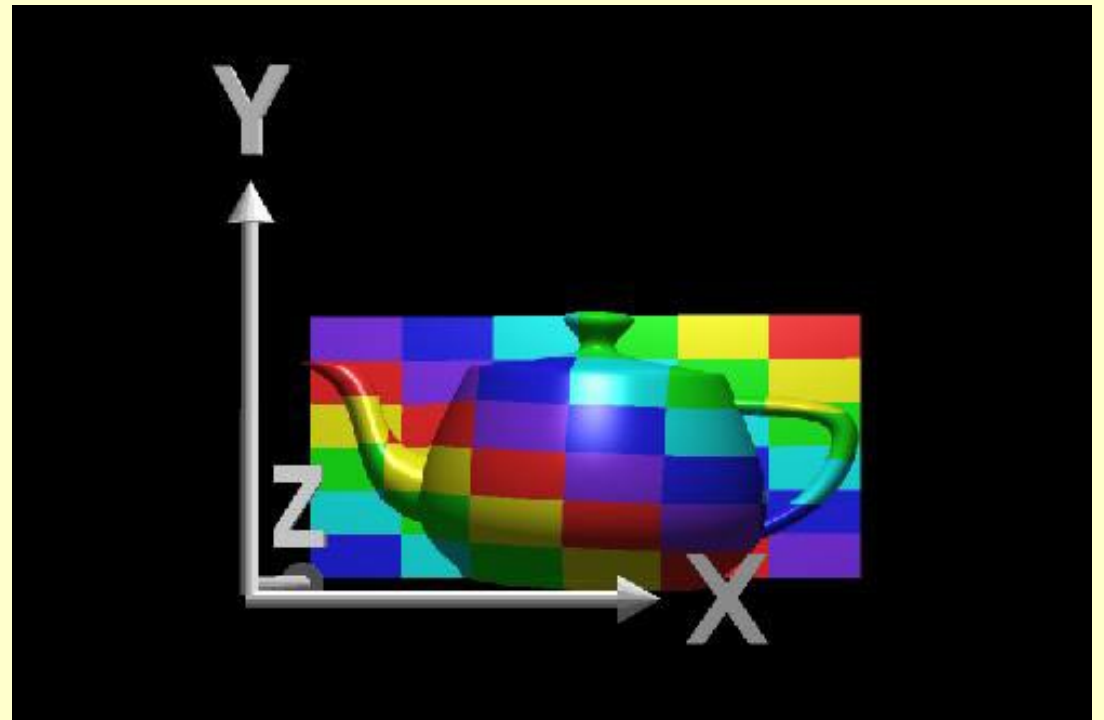
- Two-stage mapping
- Reverse projection

Planar Mapping

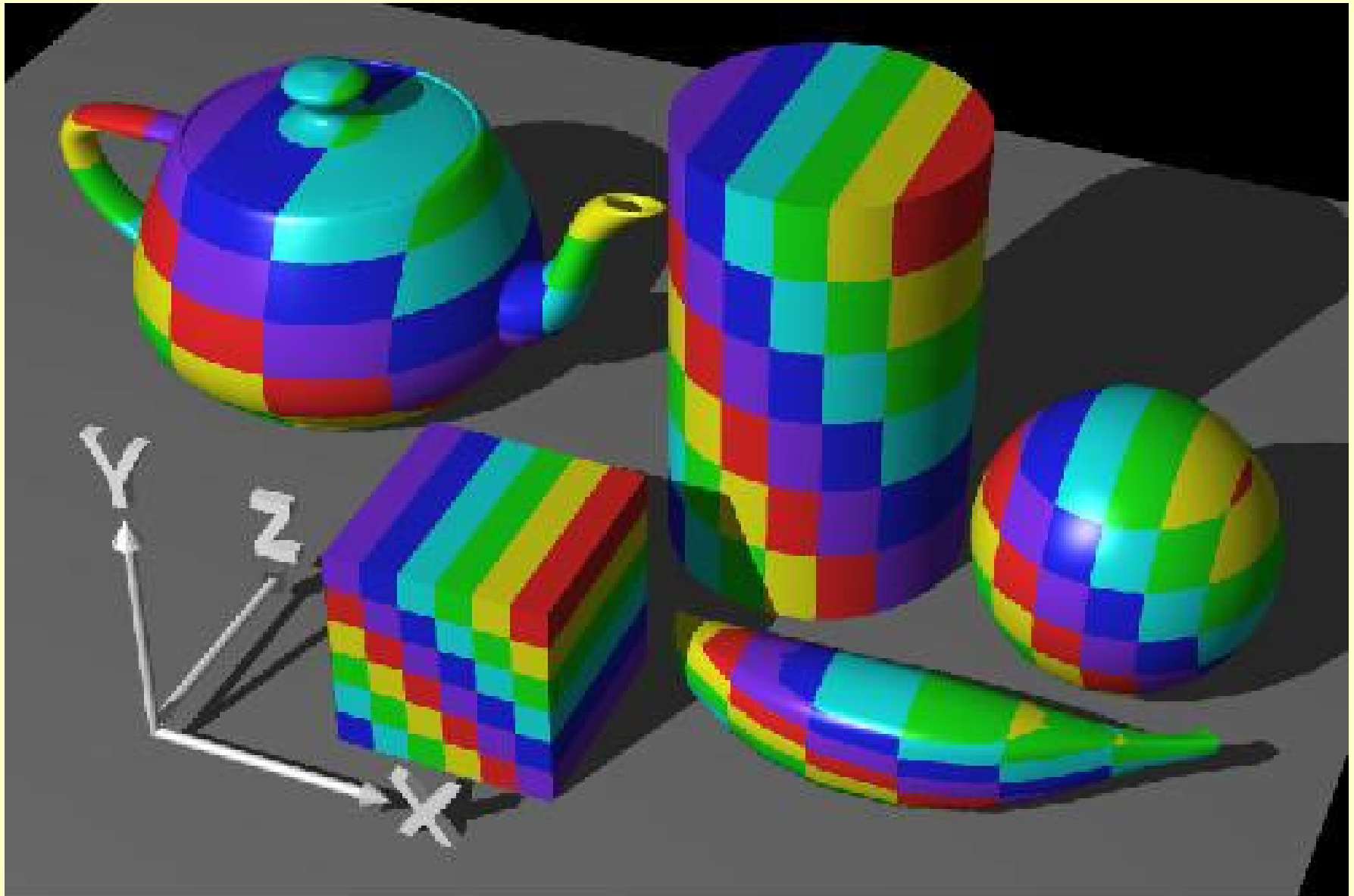
Parallel Projection of Texture

Reverse Map Position to Texture Coordinate

$$(u, v) = \left(\frac{x - x_1}{x_r - x_1}, \frac{y - y_1}{y_r - y_1} \right)$$



Planar Mapping



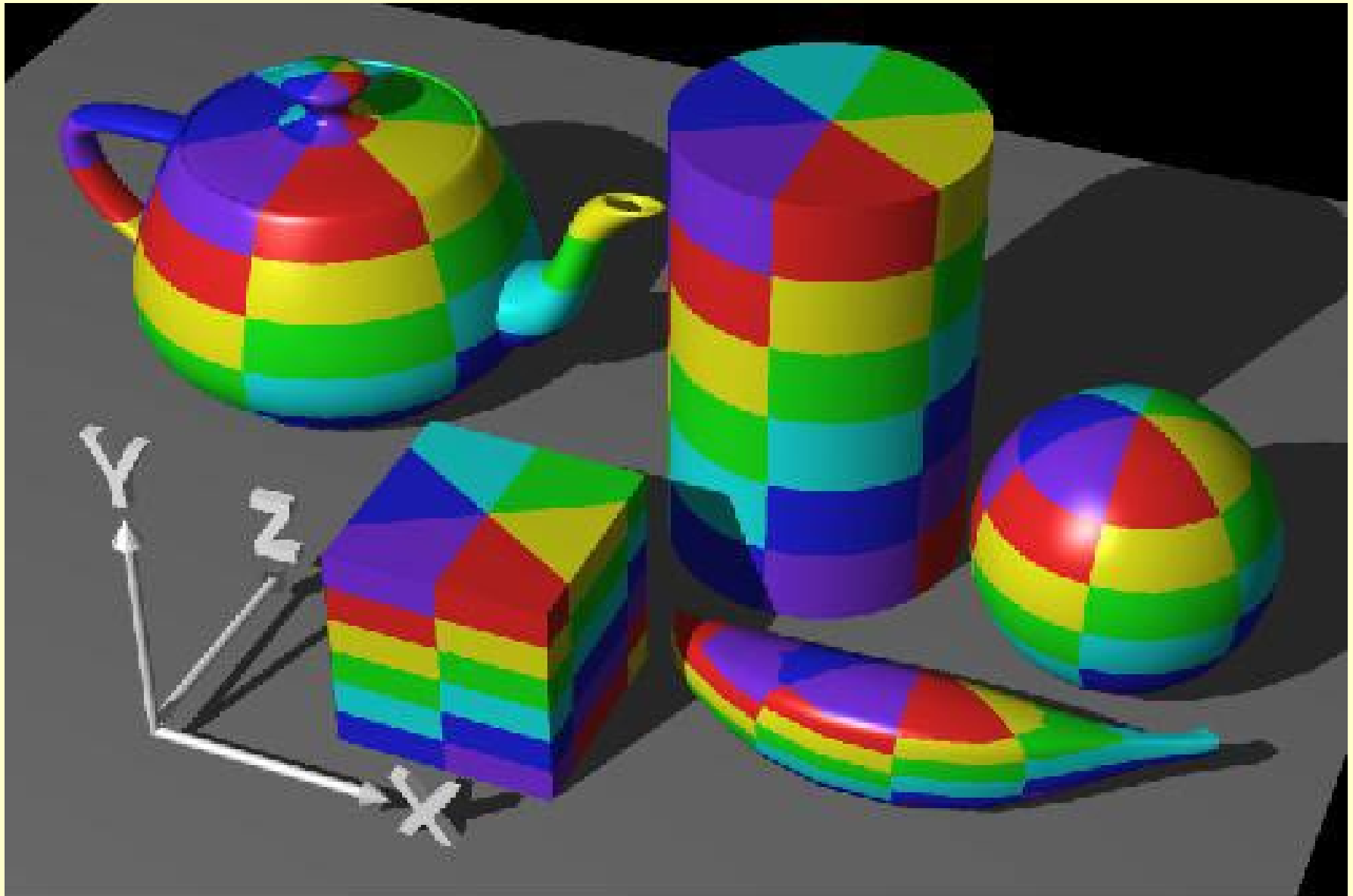
Cylindrical Mapping

For cylinder with point $(r \sin \theta, r \cos \theta, h z)$

Texture coordinate $(u, v) = (\theta/2\pi, z)$



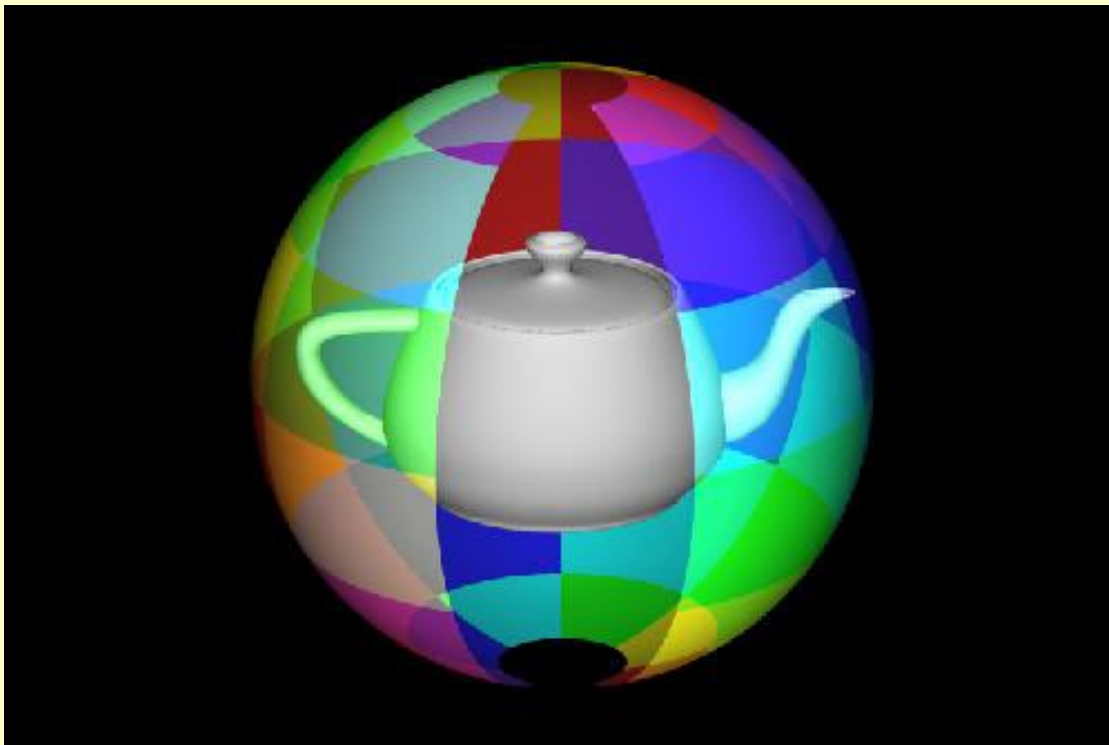
Cylindrical Mapping



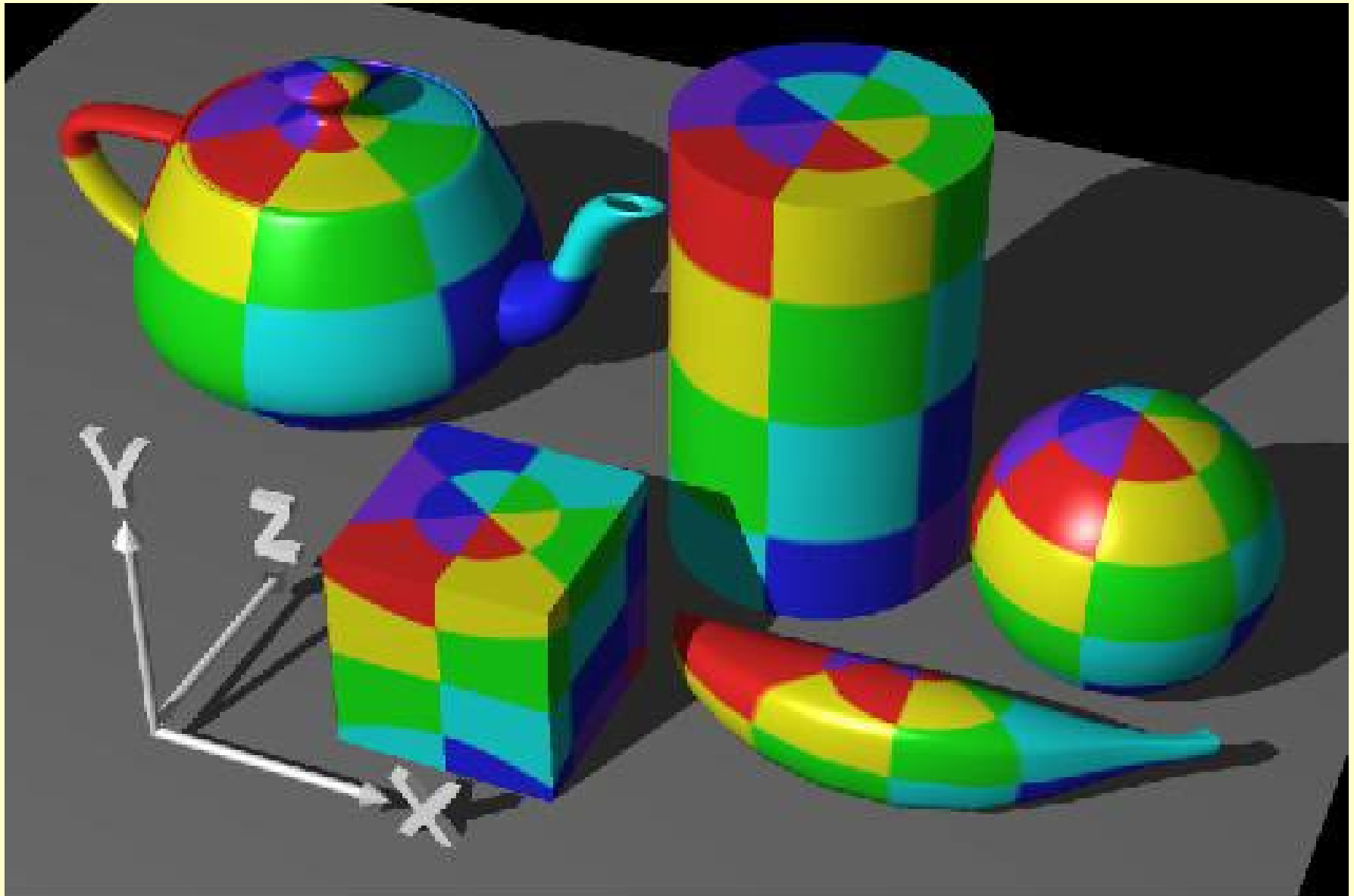
Spherical Mapping

Sphere point $(r \cos \theta \sin \phi, r \sin \theta \sin \phi, r \cos \phi)$

Texture coordinate $(u, v) = \left(\frac{\theta}{\pi/2}, \frac{\pi/2 - \phi}{\pi/4} \right)$



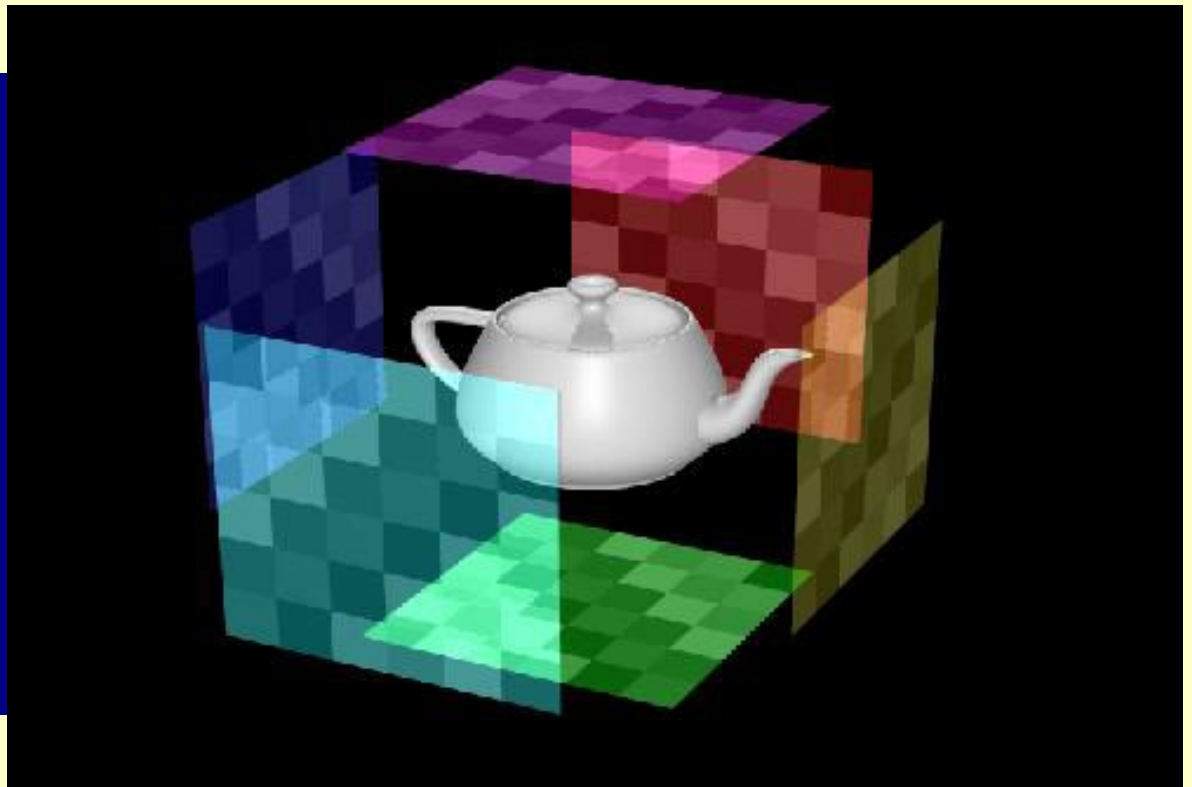
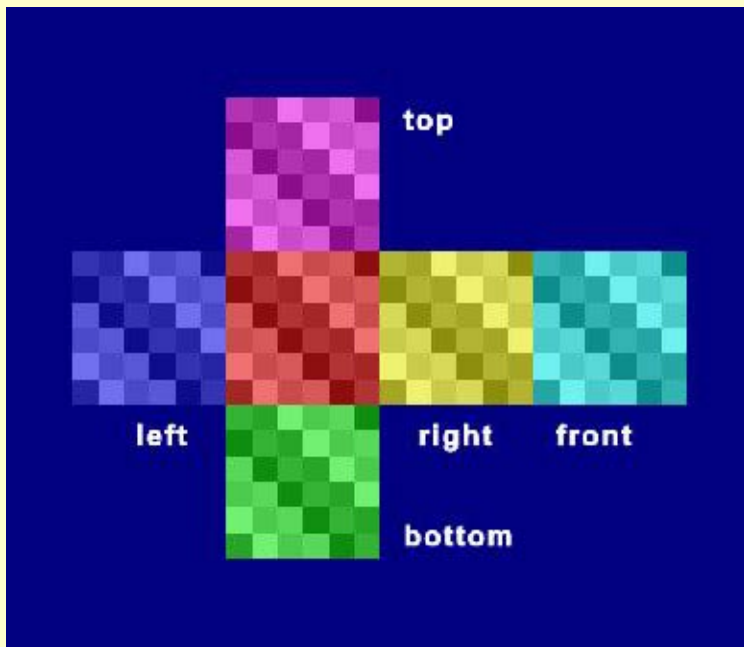
Spherical Mapping



Environment Mapping

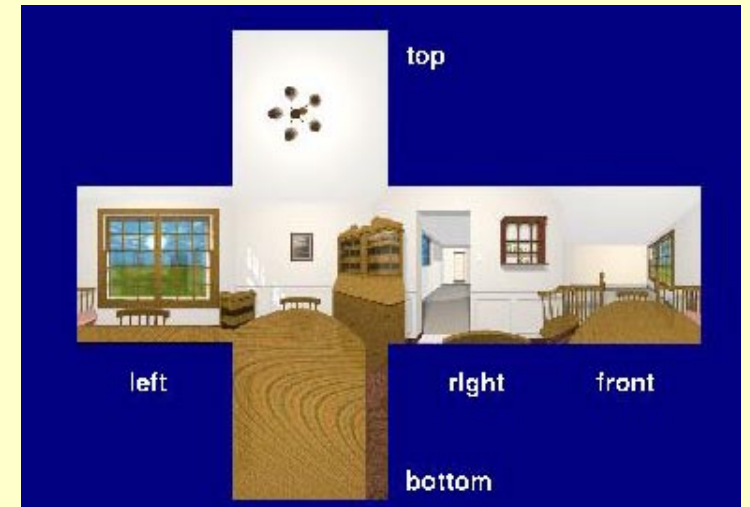
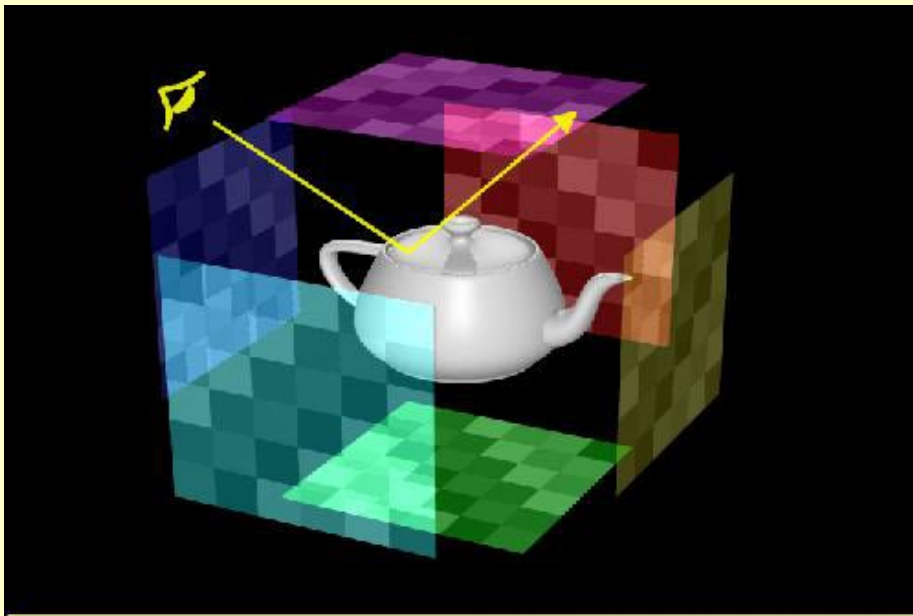
Map *vector direction* to texture coordinates

- Any mapping of *vector* to *texture* will work
- *Cube map* uses texture on six faces of cube



Reflection Mapping

Map based on *reflection direction*



Reflection Mapping

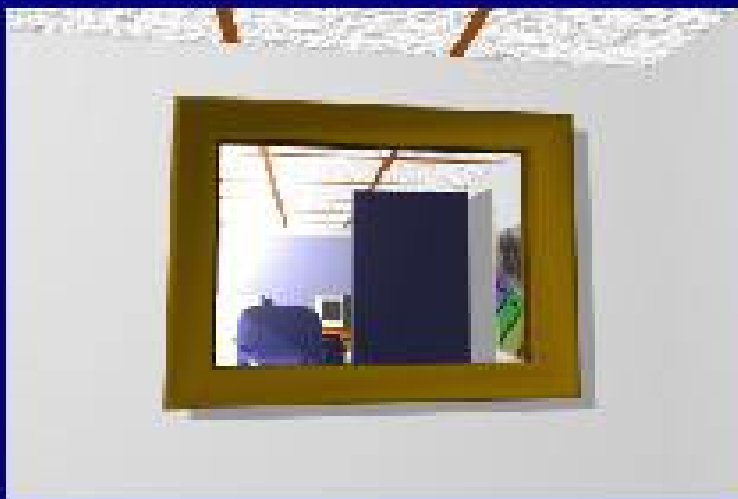


Ray Tracing



Reflection Mapping

Reflection Mapping



Reflection Mapping



Cube Environment Map

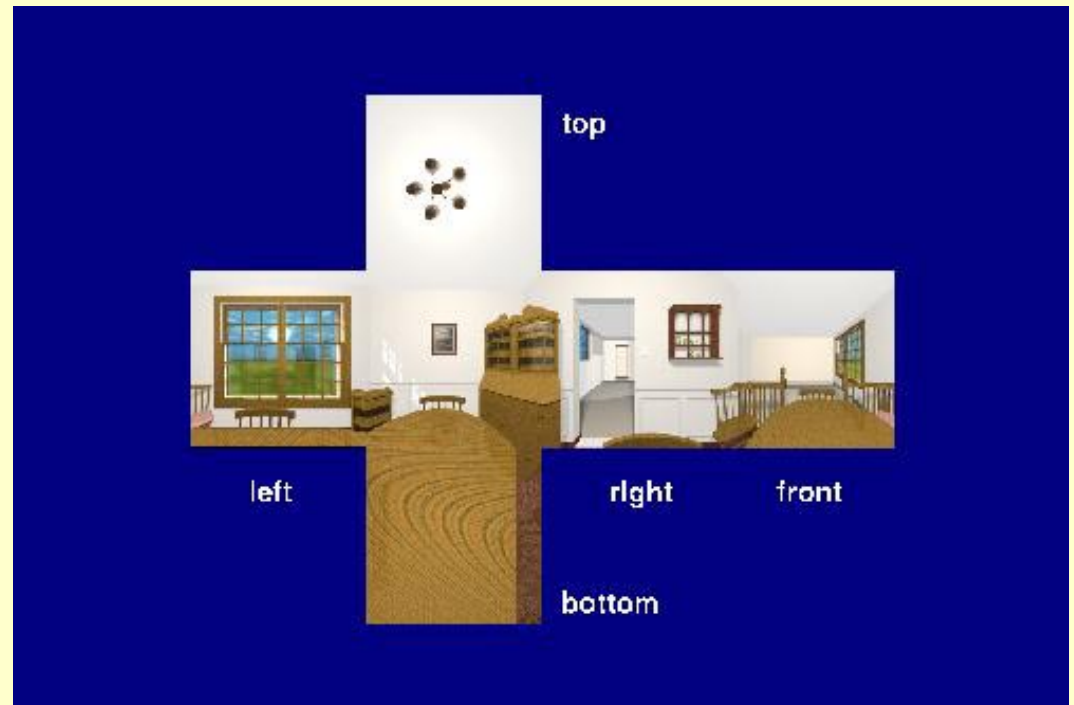
Choose cube face from largest vector component

+x: $+x > \pm y, \pm z$	+y: $+y > \pm z, \pm x$	+z: $+z > \pm x, \pm y$
-x: $-x > \pm y, \pm z$	-y: $-y > \pm z, \pm x$	-z: $-z > \pm x, \pm y$

Perspective project onto face

+x: $y/x, z/x$

Transform resulting
-1 to 1 into texture
space



Sphere Environment Map

Texture = reflection from shiny sphere

- Normal for reflection = $\hat{\mathbf{h}} = (\hat{\mathbf{v}} + \hat{\mathbf{r}}) / |\hat{\mathbf{v}} + \hat{\mathbf{r}}|$
- Transform x and y components to texture coord

Advantages

- Easy to acquire
- Easy to use

Disadvantages

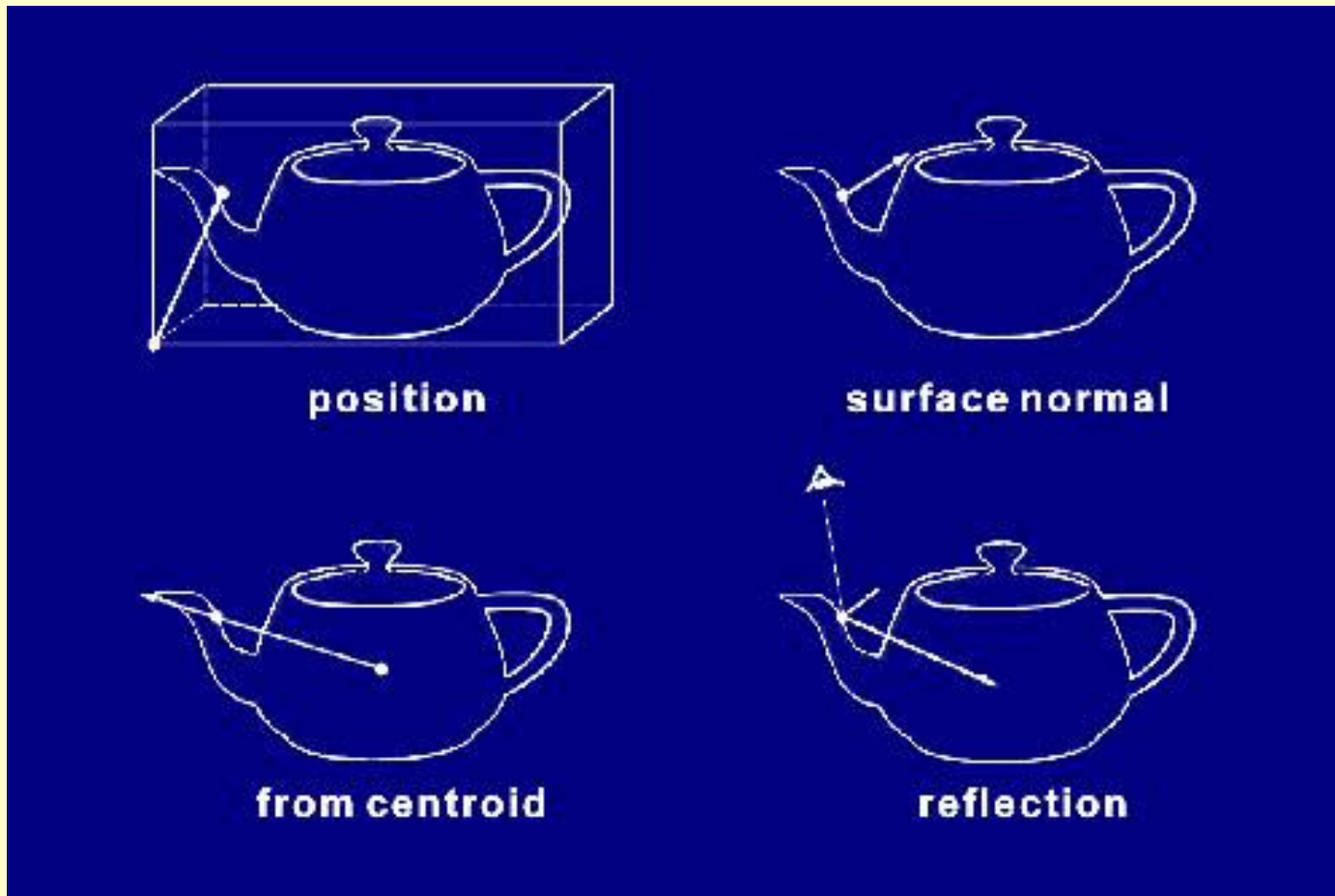
- Fixed view
- Poor sampling near edge



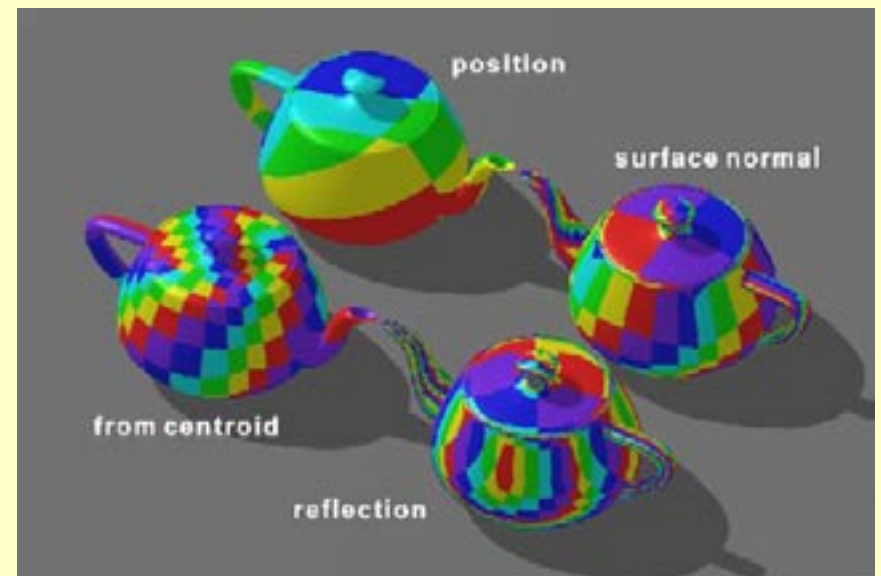
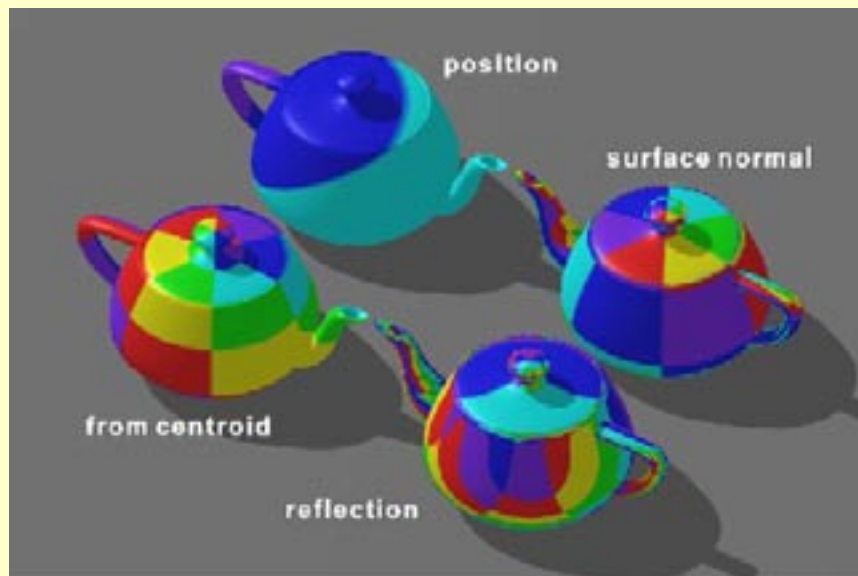
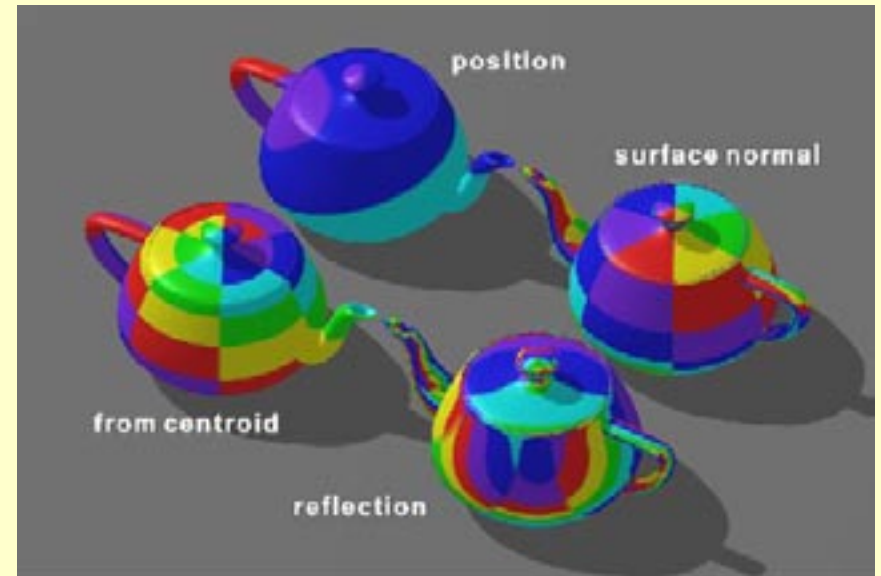
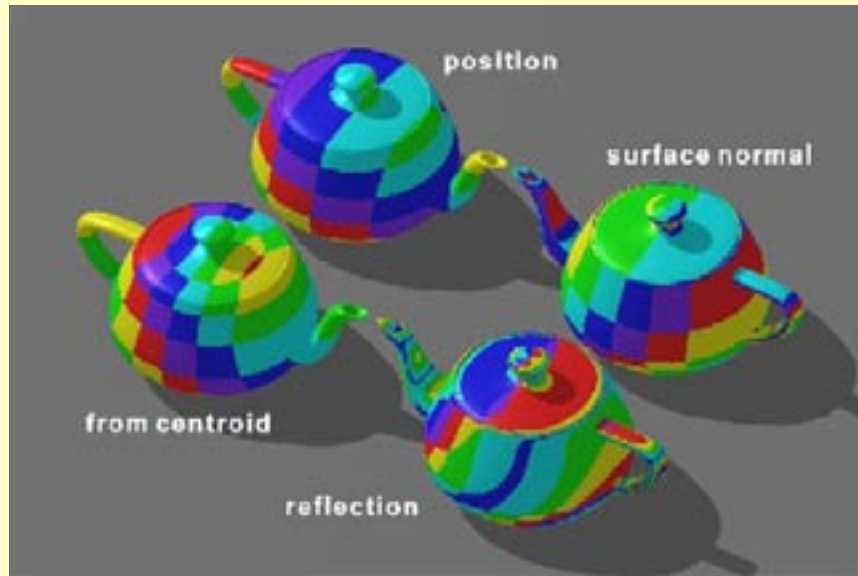
Map Entity vs. Map Shape

Map shape: sphere, cylinder, cube, plane, ...

Map entity: position, normal, reflection vector, ...

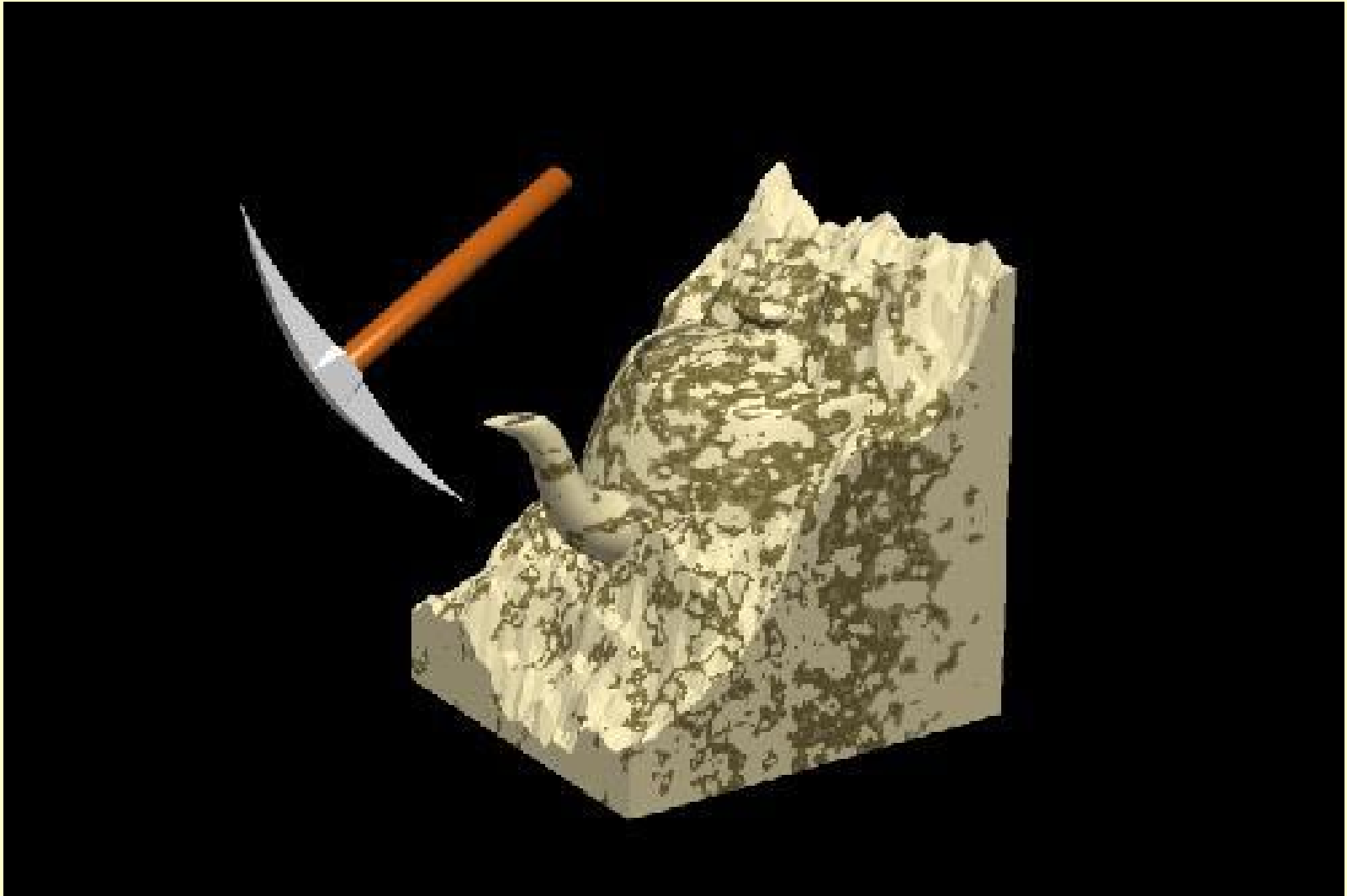


Map Entities



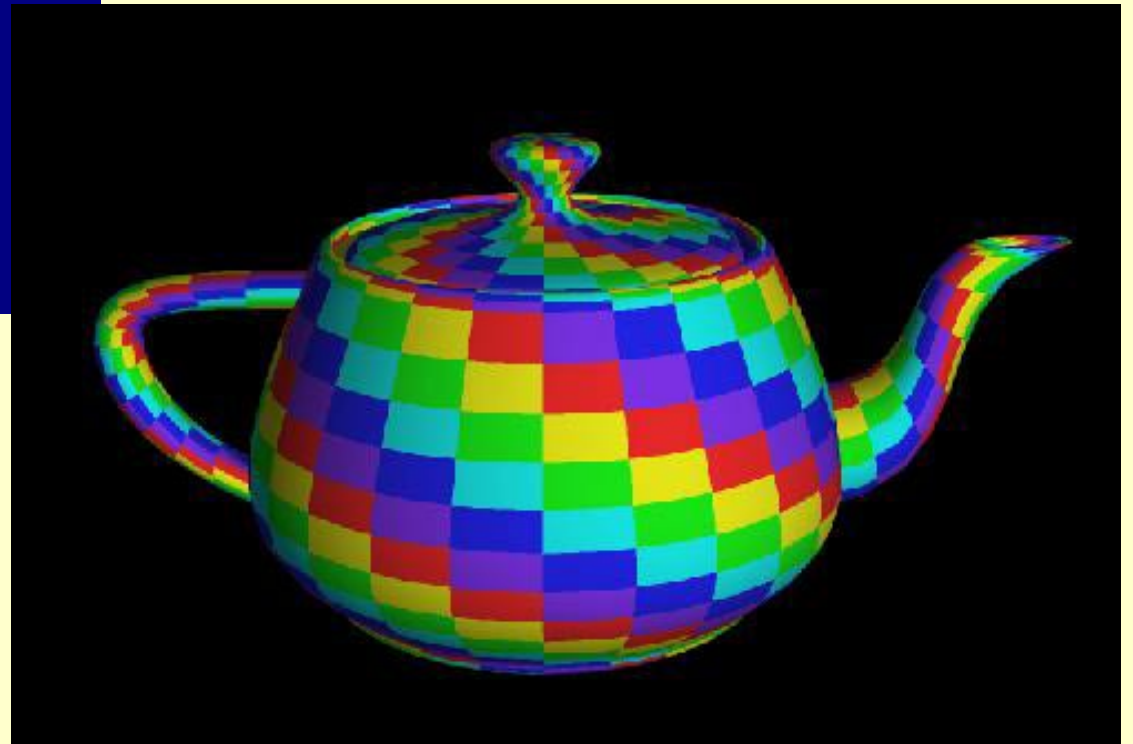
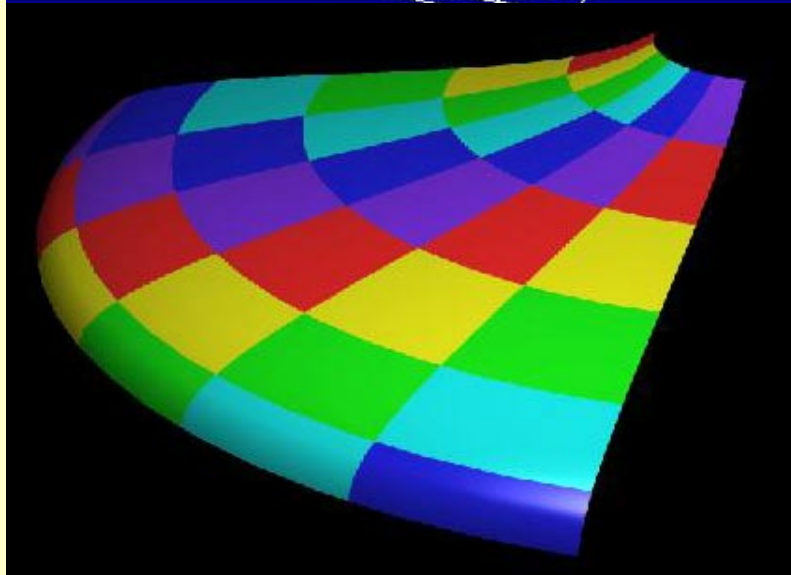
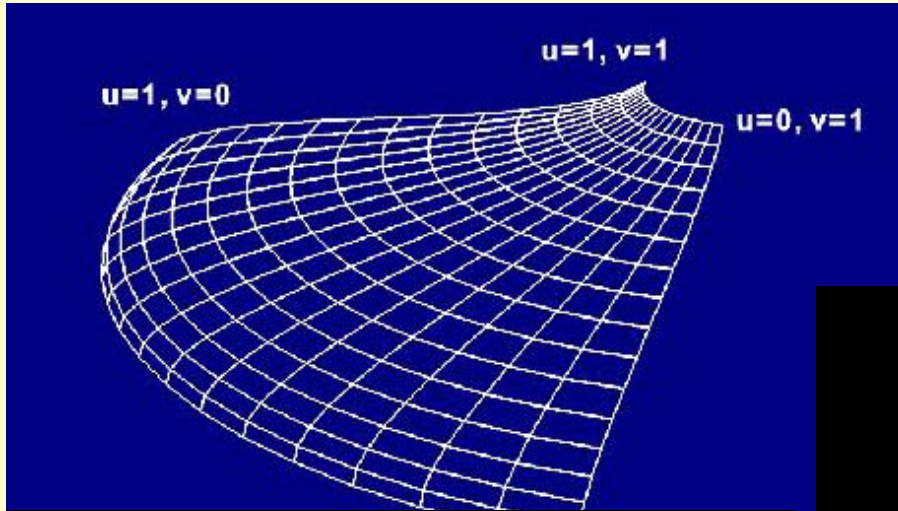
Solid/3D texture

3D Position in 3D volume texture



Parametric Patches

Use scaled surface u, v for texture u, v



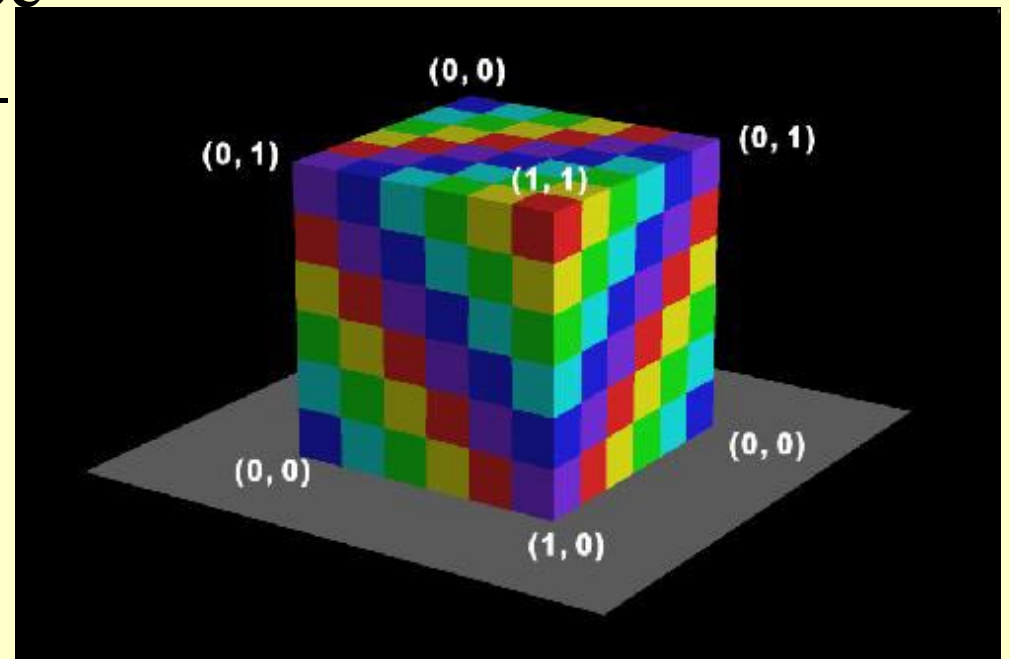
Mapping onto Polygons

Like parametric surfaces, but use explicit vertex texture coords

Interpolation issues

- screen space interp results in errors from nonlinearity and lack of rotational invariance
- use small polygons to minimize artifacts

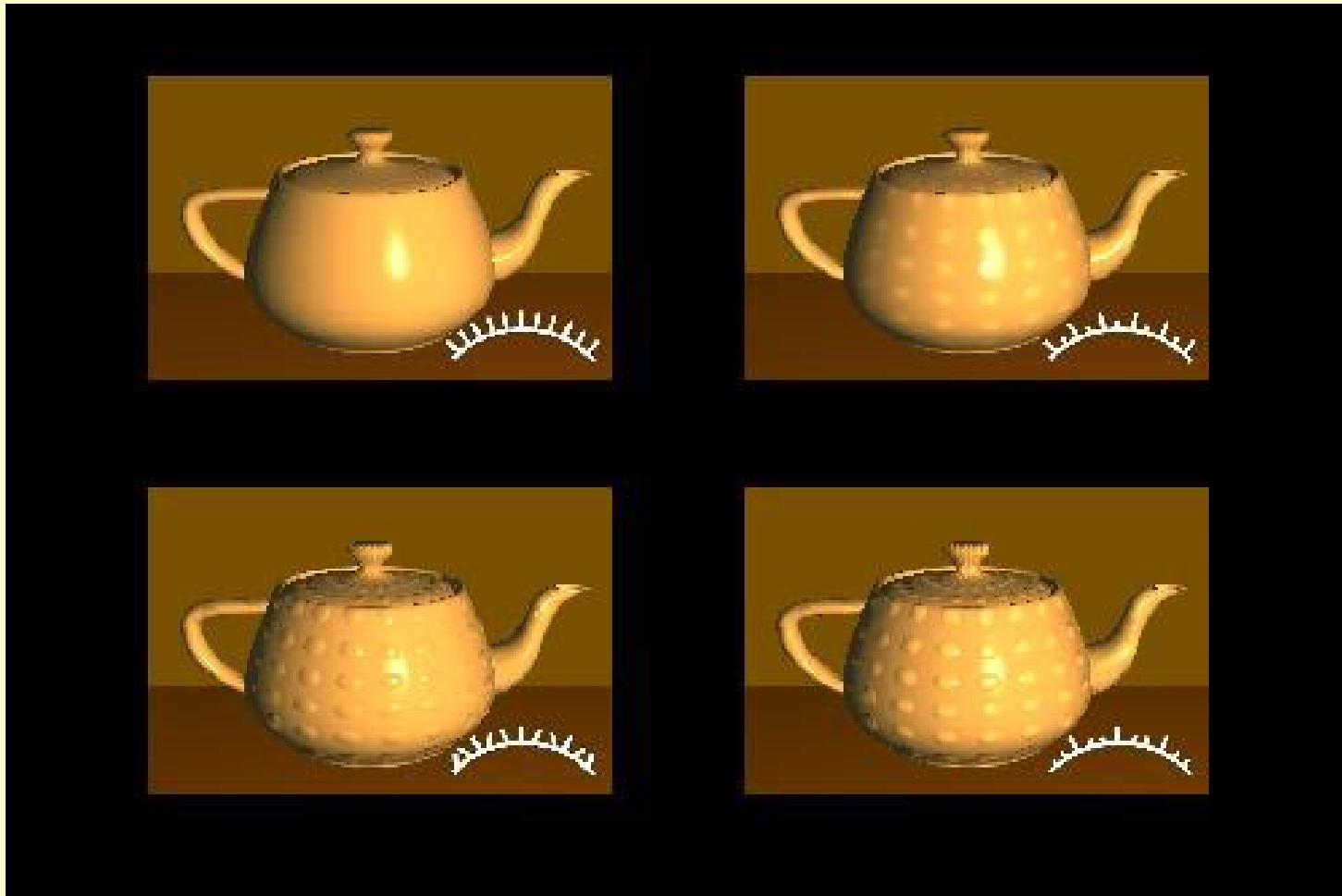
Correct solution: actual projection at each pixel



Bump Mapping

Purterb surface normal

- Simulate minor shape variations



Bump Mapping



Displacement Mapping

Actually perturb surface



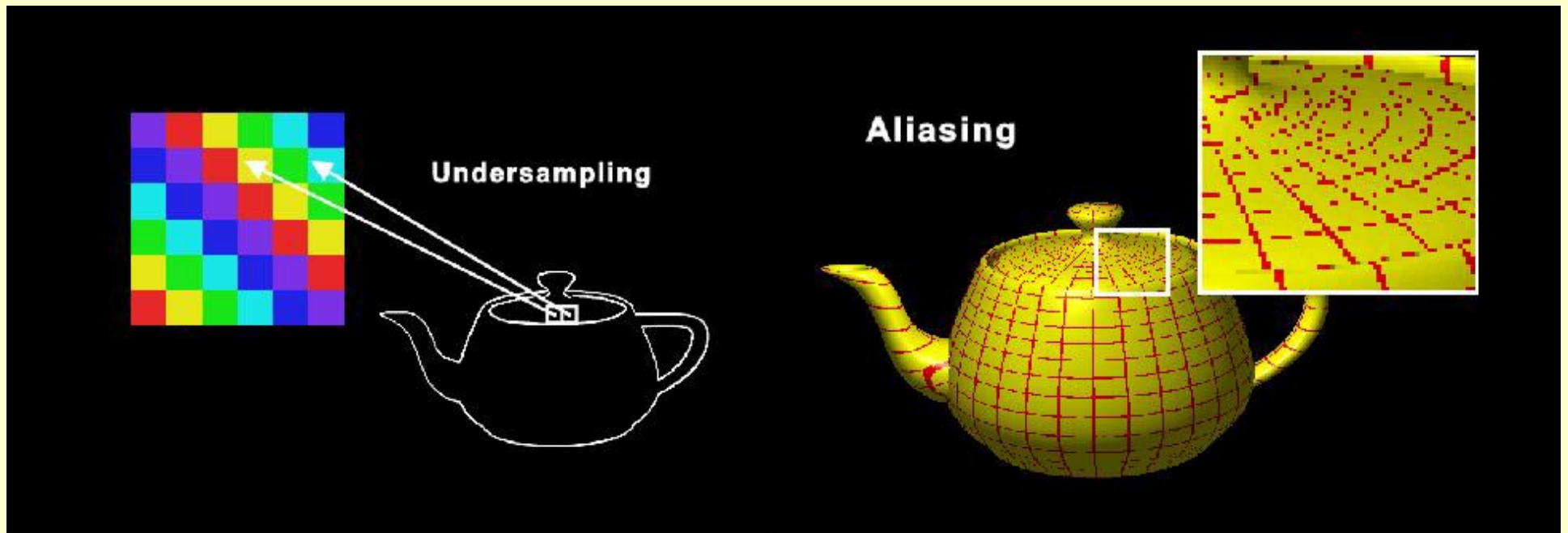
Texture Sampling

Oversampling: shows limited texture resolution

- Magnification

Undersampling: aliasing

- Minification

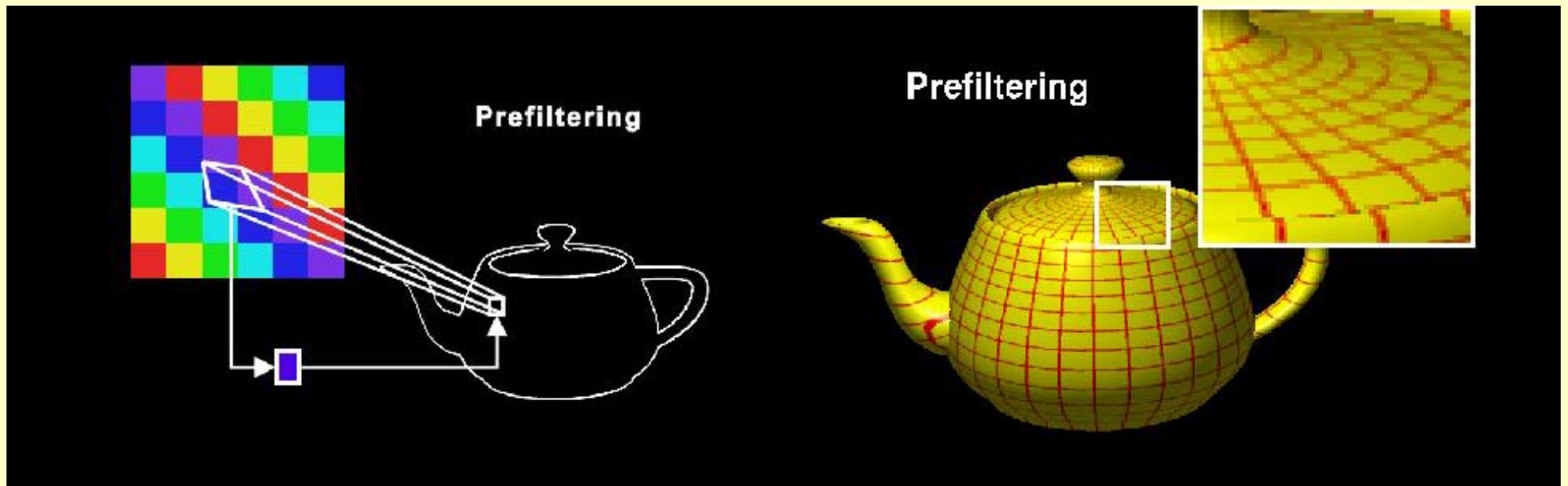


Texture Filtering

Similar to pixel antialiasing

BUT texture is known in advance

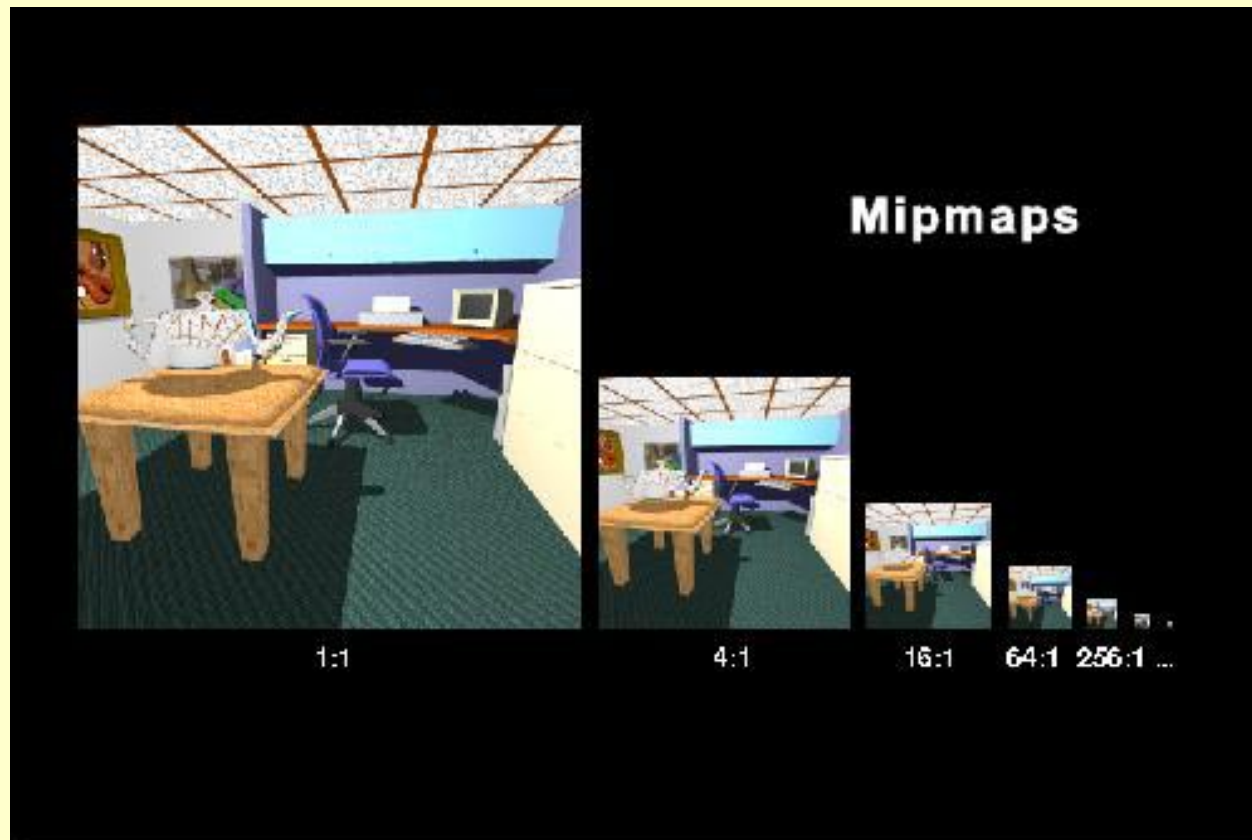
- Can improve overall antialiasing by filtering texture first
- Do faster and better by using prefiltering
 - Project pixel to texture, filter in texture space



Texture Prefiltering

MIPMap (Williams 78)

- Pre-filter at a sequence of resolutions
- Use one or several closest to correct filter size



Mipmap Reconstruction

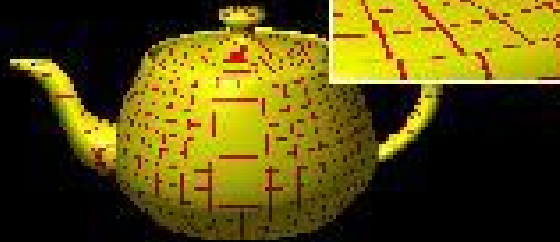
Trilinear filtering:

- Find area in texture
- Average texels within two closest mipmaps
- Average between two closest mipmaps



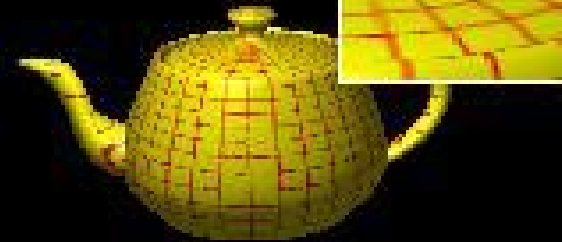
Texture + Pixel Antialiasing

15.4 seconds



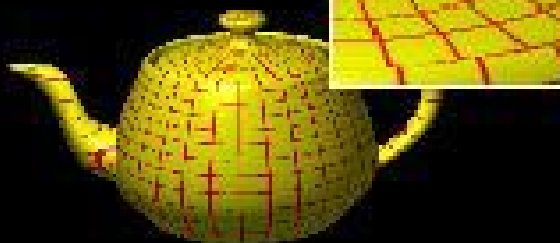
No Antialiasing

36.3 seconds



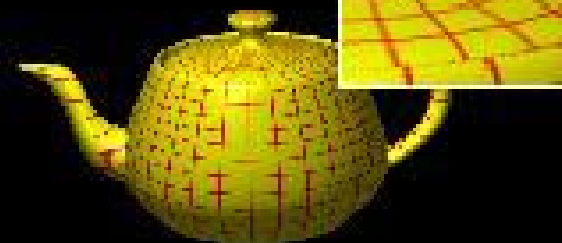
Mipmapping

53.2 seconds



9x Supersampling

136.0 seconds



Mipmap + Supersample