

# Multi-Agent Systems

Overview and Research Directions (Ch. 17.5–17.6)

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## Bookkeeping

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- HW 3 out; please start it early (earlier)
  - A note: late penalty will be strict for HW 3-5
  - **Summary: if Blackboard says it's late, it's late**
- Midterm: currently scheduled for 10/18 (Tuesday).
- Would we prefer 10/13 (the preceding Thursday)?
  - We would not. 10/18 it is.

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## Today's Class

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- What's an agent?
- Multi-Agent Systems
  - Cooperative multi-agent systems
  - Competitive multi-agent systems
    - Game time!
- MAS Research Directions
  - Organizational structures
  - Communication limitations
  - Learning in multi-agent systems

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## What's an Agent?

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## What's An Agent? (Redux)

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- Weiss, p. 29 [after Wooldridge and Jennings]:
  - “An **agent** is a computer system that is **situated** in some **environment**, and that is capable of **autonomous action** in this environment in order to meet its design objectives.”
- Russell and Norvig, p. 7:
  - “An agent is just something that perceives and acts.”

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## What's An Agent? II

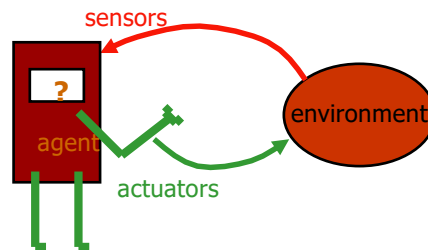
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- Ferber, p. 9: “An agent is a physical or virtual entity [which]
  - Is capable of **acting** in an **environment**,
  - **Can communicate** directly with other agents,
  - Is driven by a set of **tendencies...**,
  - Possesses **resources** of its own,
  - Is capable of **perceiving** its environment...,
  - Has only a **partial representation** of this environment...,
  - Possesses **skills** and can offer **services**,
  - May be able to **reproduce** itself,
  - Whose behavior tends towards **satisfying its objectives**, taking account of the resources and skills available to it and depending on its perception, its representations and the communications it receives.”

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## OK, What's An Environment?

- Any system that has inputs and outputs is **situated** in an **environment** of sorts
- We've also said **world**
  - **World state**: a snapshot of an environment



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## What's Autonomy?

- Jennings and Wooldridge, p. 4:
  - “[In contrast with objects] ... **agents encapsulate behavior**, in addition to state.
  - An **object** does not encapsulate behavior: it has no control over the execution of methods – if an object *A* invokes a method *m* on an object *B*, then *B* has no control over whether *m* is executed or not – it just is.
  - In this sense, object *B* is not autonomous, as it has no control over its own actions.
  - Because of this ..., we do not think of agents as invoking methods (actions) on agents – rather, we tend to think of them **requesting** actions to be performed.”
- Is an if-then-else statement autonomous?

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## So Now What?

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- If those definitions aren't useful, is there a useful definition?
- Should we bother trying to create "agents" at all?



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## A Pause to Vote... (more on which later)

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- For Tic-Tacs, Skittles, licorice, gummi bears:



- Do you **prefer** Skittles or gummi bears?
- Do you **prefer** licorice or Tic-Tacs?
- **Which of these is best?**
- Sort the candy from **best to worst (1 = best; no ties)**

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# Multi-Agent Systems

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## Multi-Agent Systems

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- Jennings et al.'s key properties:
  - Situated [existing in relation to some environment]
  - Autonomous
  - Flexible:
    - Responsive to dynamic environment
    - Pro-active / goal-directed
    - **Social interactions with other agents and humans**
- Research questions: How do we design agents to:
  - **Interact effectively...**
  - ...To solve a wide range of problems...
  - ...In many different environments?

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## What are Multi-Agent Systems?

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- Thus a multiagent system contains a number of agents that:
  - Interact through communication;
  - Are able to act in an environment;
  - Have different “spheres of influence” (which may coincide)
  - And will be linked by other (organizational) relationships

*Slide: M. J. Wooldridge & S. Parsons*

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## Why Multi-Agent Systems?

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- Some of the trends in computing:
  - Ubiquity, interconnection, intelligence, delegation
  - The Internet of Things, self-steering cars, home automation devices
- What advantages does it offer over the alternatives?
- In what circumstances is it useful?

*Slide: Matthew E. Taylor, with thanks*

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## Possible Motivations for MAS

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- Task is too complex for one agent
- Task is inherently distributed
  - Ex. soccer (goalie, striker, defenders...)
- Several resource-bound agents are cheaper (or more feasible to build) or faster than a single, more capable agent
- Multiple agents are more robust because they offer redundancy
  - Ex. one fails, others take its place; **graceful degradation**

*Slide adapted from Introduction to AI Robotics, R. Murphy (MIT Press 2000) for 2<sup>nd</sup> edition*

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## Aspects of Multi-Agent Systems

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- Cooperative vs. competitive
- Homogeneous vs. heterogeneous
- Interaction protocols and languages
- Organizational structure
- Mechanism design / market economics
- Learning

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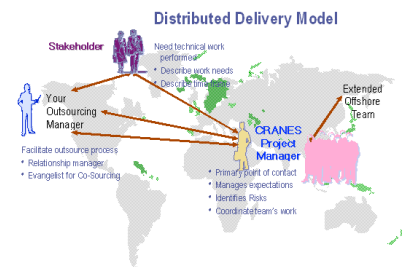
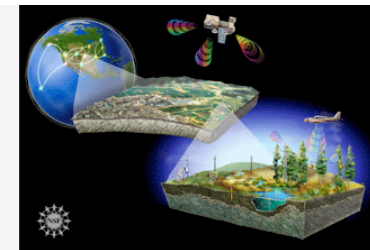
## Topics in MAS

- Cooperative MAS:
  - Distributed problem solving: Less autonomy
    - (At least in a certain sense)
  - Distributed planning: Models for cooperation and teamwork
- Competitive or self-interested MAS:
  - Distributed rationality: Voting, auctions
  - Negotiation: Contract nets
  - Strictly adversarial interactions ← least complex

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## Some Cooperative MAS Domains

- Distributed sensor network establishment
- Distributed vehicle monitoring
- Distributed delivery



NSE: [www.linkedin.com/pub/3426-595-vehicle-cto-customers-1001-bus-truck-birds-offline](http://www.linkedin.com/pub/3426-595-vehicle-cto-customers-1001-bus-truck-birds-offline) or [www.cranesoft.com/alliances/fluid/offshore-delivery](http://www.cranesoft.com/alliances/fluid/offshore-delivery)

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## Distributed Sensing & Monitoring

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- Distributed sensing:
  - Distributed sensor network establishment:
    - Locate sensors to provide the best coverage
    - Centralized vs. distributed solutions
  - Track vehicle/other movements using multiple sensors
- Distributed vehicle monitoring:
  - Control sensors and integrate results to track vehicles as they move from one sensor's "region" to another's
  - Centralized vs. distributed solutions

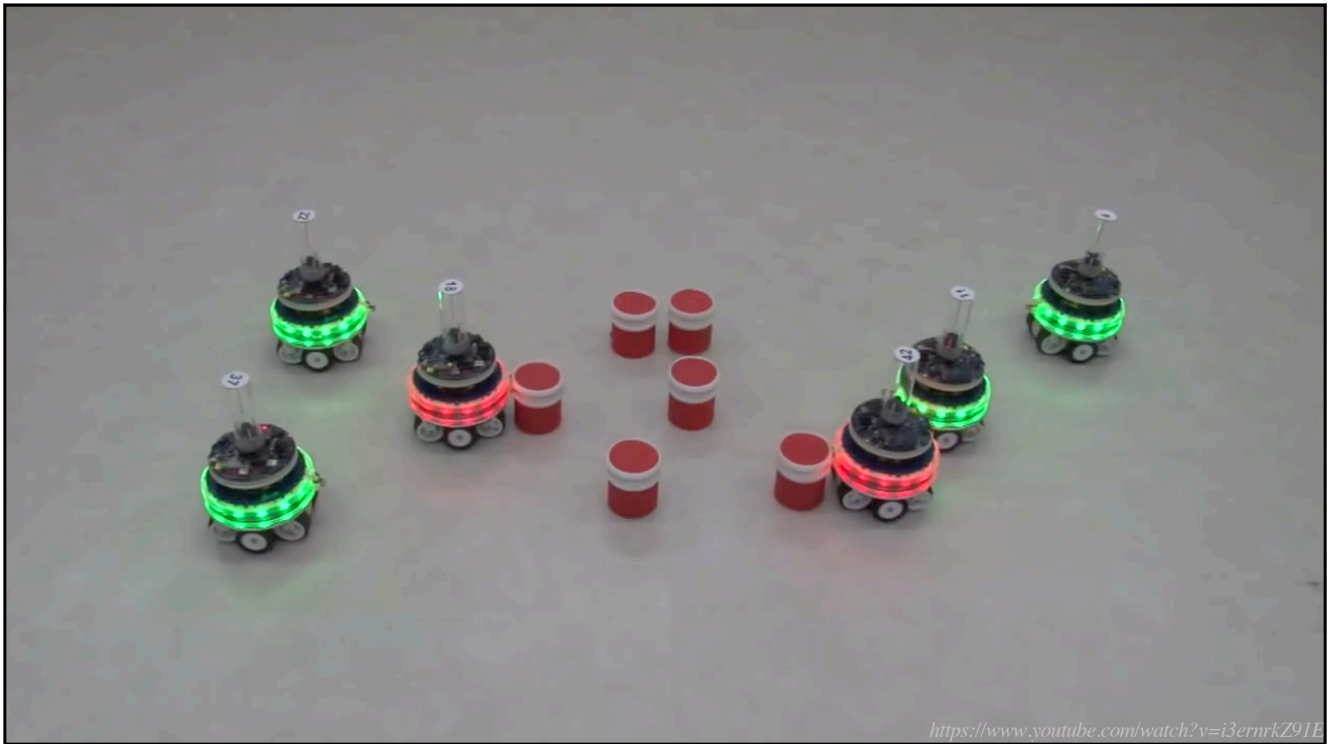
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## Distributed Delivery

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- Logistics problem: move goods from original locations to destination locations using multiple delivery resources (agents)
- Dynamic, partially accessible, nondeterministic environment (goals, situation, agent status)
- Centralized vs. distributed solution

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## Competitive Multi-Agent Systems



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## Games and Game Theory

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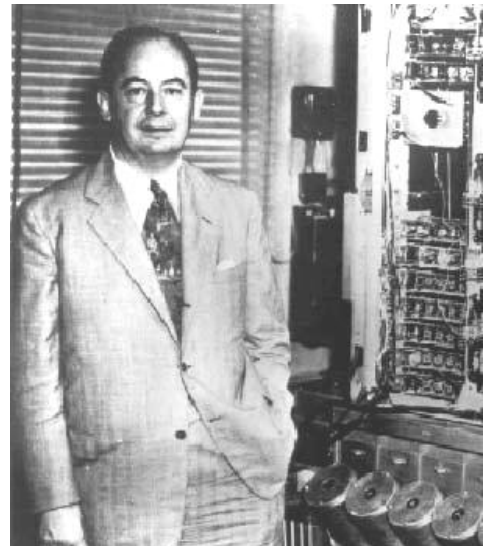
- Much effort on developing programs for artificial games like chess or poker, played for entertainment
- Larger issue: account for, model, and predict how agents (human or artificial) **interact with other agents**
- **Game theory** accounts for a mixture of cooperative and competitive behavior
- Applies to zero-sum and non-zero-sum games

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## Game Theory

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- Defined by von Neumann & Morgenstern
  - von Neumann, J., and Morgenstern, O., (1947).  
The Theory of Games and Economic Behavior.
- Covers both cooperative and non-cooperative situations
- Developed and used in economics, now used to model artificial agents
- Provides a powerful model and practical tools to think about interactions among a set of autonomous agents



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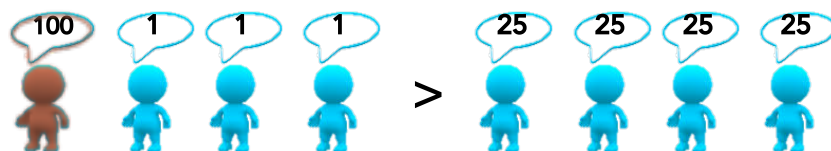
## Basic Ideas of Game Theory

- **Game theory** studies how strategic interactions among rational players produce outcomes with respect to the players' preferences (utilities)
  - Outcomes might not have been intended
- Game theory offers a general theory of strategic behavior
- Generally depicted in mathematical form
- Plays important role in economics, decision theory and multi-agent systems
- So how do we describe the utility of states across many agents?
  - Social welfare; Pareto optimality; Nash equilibria; other equilibria

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## Social Welfare

- **Social welfare**, or global utility:
  - Sum of all agents' utility
  - If state  $s$  maximizes social welfare, it is also Pareto-optimal (but not vice versa)
- Somewhat poorly named
  - Sum  $\neq$  average
  - Allocation of resources typically affects influence
    - e.g., you get to take 1 turn per point accrued



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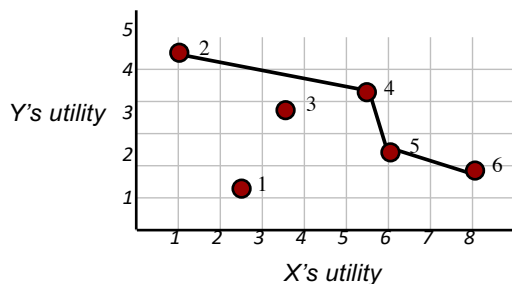
## Pareto Optimality

- An outcome is **Pareto optimal** if there is **no other outcome that all players would prefer**.
  - “a state ... from which it is impossible to [change] so as to make any one individual better off without making at least one individual worse off.” – *Wikipedia*
  - There can be multiple Pareto optimal solutions.
- If 2 students on a project both have Bs, would they switch to an A and a C?
  - No – if those are the choices, B/B is Pareto optimal
  - If A/A is an option, B/B is no longer Pareto optimal

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## Pareto Optimality

- $s$  is a Pareto-optimal solution iff
  - $\forall s' (\exists x U_x(s') > U_x(s) \rightarrow \exists y U_y(s') < U_y(s))$
  - I.e., if X is better off in  $s'$ , then some Y must be worse off
  - There is no other outcome that **all** players would prefer



Which solutions  
are Pareto-optimal?

Which solution(s)  
maximize global utility  
(social welfare)?

$$\text{State 1} = 1.25 + 2.5 = 3.75$$

$$\text{State 2} = 1 + 4.25 = 5.25$$

$$\text{State 3} = 3.5 + 3.75 = 7.25$$

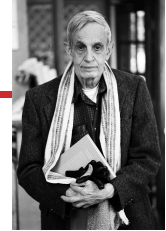
$$\text{State 4} = 5.5 + 3.25 = 8.75$$

$$\text{State 5} = 6 + 2.25 = 8.25$$

$$\text{State 6} = 8 + 1.75 = 9.75$$

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## Nash Equilibrium



- Occurs when each player's strategy is optimal, **given** strategies of the other players
- No player benefits by **unilaterally** changing strategy while others stay fixed
- Every finite game has at least one Nash equilibrium in either pure or mixed strategies (proved by John Nash)
  - J. F. Nash. 1950. Equilibrium Points in  $n$ -person Games. Proc. National Academy of Science, 36
  - Nash won 1994 Nobel Prize in economics for this work
  - Read *A Beautiful Mind* by Sylvia Nasar (1998) and/or see the 2001 film

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## Stability

- If an agent can always maximize its own utility with a particular strategy (regardless of other agents' behavior) then that strategy is **dominant**
  - Strategy  $s$  **dominates**  $s'$  iff:
    - Outcome (for player  $p$ ) of  $s$  is better than the outcome of  $s'$  **in every case**
- A **set** of agent strategies is in **Nash equilibrium** if each agent's strategy  $S_i$  is locally optimal, *given* the other agents' strategies
  - No agent has an incentive to change strategies
  - Hence this set of strategies is **locally stable**

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## Prisoner's Dilemma

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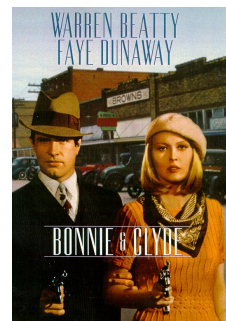
- Famous example of game theory
- Will two prisoners cooperate to minimize total loss of liberty or will one of them betray the other so as to go free?
- Strategies must be undertaken without full knowledge of what other players will do
- Players adopt dominant strategies, but they don't necessarily lead to the best outcome
- Rational behavior leads to a situation where everyone is worse off

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## Bonnie & Clyde

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- Bonnie and Clyde are arrested. They're questioned separately, unable to communicate. They know the deal:
  - If **both** proclaim innocence (deny involvement), they will both get short sentences
  - If **one confesses** and the **other doesn't**, the confessor gets a heavy sentence and the denier gets a light sentence
  - If **both confess**, both get moderate sentences
- What should Bonnie do?
- What should Clyde do?



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## Exercise: Prisoner's Dilemma

- <Bonnie's sentence, Clyde's sentence>

<i>B</i> \ <i>C</i>	Confesses	Denies
Confesses	(4, 4)	(8, 1)
Denies	(1, 8)	(3, 3)

- Play 1 round – what are results?
- Switch partners
- Play 5 rounds, keeping track of total years

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## Prisoner's Dilemma: Analysis

- Pareto-optimal and social welfare maximizing solution: **Both agents deny**
- Dominant strategy and Nash equilibrium: **Both agents confess**

- **Why?**

<i>B</i> \ <i>C</i>	Confesses	Denies
Confesses	(4, 4)	(8, 1)
Denies	(1, 8)	(3, 3)

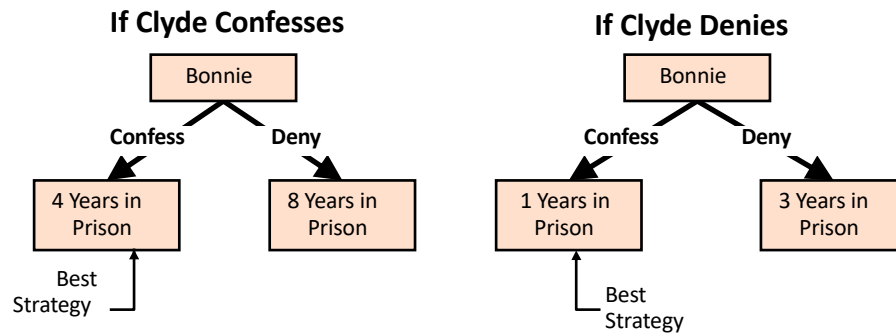
- Because if you deny and the other confesses, it's the worst case
  - No agent has incentive to change strategies, **given that others do not change**

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## Bonnie's Decision Tree

No wonder Economics is called "the dismal science"

There are two cases to consider:



Dominant strategy **for Bonnie** is to confess because no matter what Clyde does she is better off confessing.

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## Iterated Prisoner's Dilemma

- Rational players should always confess in a PD situation
- In real situations, people don't always do this
- Why not? Possible explanations:
  - People aren't rational
  - Morality
  - Social pressure
  - Fear of consequences
  - Evolution of species-favoring genes
- Which make sense? How can we formalize?

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## Iterated PD

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- **Key idea:** We often play more than one “game” with someone
- Players have complete knowledge of past games, including their choices **and other players’ choices**
- Can choose based on whether they’ve been cooperative in past
- Simulation was first done by Robert Axelrod (Michigan) where programs played in a round-robin tournament

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## Strategies

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- Simple single-agent strategies:
  - Always deny
  - Always cooperate
  - Randomly choose
  - Pavlovian (win-stay, lose-switch): Start by always cooperating, switch to always denying when “punished” by other’s denial, switch back and forth at every such punishment
  - Tit-for-tat (TFT): “Be nice, but punish any defections”: Starts by cooperating and after that always does what the other player did on the previous round
  - Joss: A sneaky TFT that defects 10% of the time
- In an idealized (noise free) environment, TFT is both a very simple and a very good strategy
- In the IPD tournament, one winner used an initial pattern of choices to identify other players with the same programming, and then switched to all denying

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## Distributed Rationality

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How can we encourage/coax/force self-interested agents to play *fairly* in the sandbox?

- **Voting:** Everybody's opinion counts (but how much?)
- **Auctions:** Everybody gets a chance to earn value (but fairly?)
- **Contract nets:** Work goes to the highest bidder
- **Issues:**
  - Global utility
  - Stability
  - Fairness
  - Cheating and lying

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## Voting: It's Not Easy

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- How should we **rank** the possible outcomes, given individual agents' preferences (votes)?
- Six desirable properties which can't all be satisfied:
  - Every **combination of votes** should lead to a **ranking**
  - Every **pair of outcomes** should have a **relative ranking**
  - The ranking should be **asymmetric** and **transitive**
  - The ranking should be **Pareto-optimal**
  - **Irrelevant alternatives** shouldn't influence the outcome
  - **Share the wealth:** No agent should always get their way

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## Voting Protocols

- **Plurality voting:**
  - The outcome with the highest number of votes wins
  - Irrelevant alternatives can change the outcome (e.g., third-party candidates “splitting” the vote)
- **Binary voting:**
  - Agents rank sequential pairs of choices (“elimination voting”)
  - Irrelevant alternatives can still change the outcome
  - Very order-dependent
- **Borda voting:**
  - Agents’ rankings are used as weights, which are summed across all agents
  - Agents can “spend” high rankings on losing choices, making their remaining votes less influential

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## Voting...



- Plurality results:
  - Most #1 votes: \_\_\_\_\_
- Elimination (bracket) results:
 

GB	
S	
L	
TT	
- Borda results:
  - Score(candy) =  $[4 \times (\# \text{ 1st place votes})] + [3 \times (\# \text{ 2nd})] + [2 \times (\# \text{ 3rd})] + [1 \times (\# \text{ 4th})]$
  - TT = \_\_\_\_\_, S \_\_\_\_\_, L \_\_\_\_\_, GB \_\_\_\_\_

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## Voting game

Discuss... did we achieve global social welfare? Fairness? Were there interesting dynamics?

- Using *plurality (1/0)* voting to select a winner:
  - The winner is the candidate with the most votes
  - The naive strategy is to vote for your top choice – is that best?
- Using *elimination* to select a winner:
  - 1<sup>st</sup> and 2<sup>nd</sup> choices can compete, so 3<sup>rd</sup> or 4<sup>th</sup> choice comes in 2<sup>nd</sup>
    - Different people use different strategies – how does that change it?
- Using *Borda (1..k)* voting:
  - Everybody ranks the k candidates that are running in that round
  - Your top choice receives k votes; your second choice, k-1, etc.
  - The winner is the candidate with the most votes
  - Borda voting is often used in combination with a runoff
    - Eliminate the lowest-ranked candidates and try again – how does that change it?

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## Auctions

- Many different types and protocols
- All of the common protocols yield Pareto-optimal outcomes
- **But...** bidders can agree to artificially lower prices in order to cheat the auctioneer
- What about when the colluders cheat each other?
  - (Now that's really not playing nicely in the sandbox!)

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## Learning in MAS

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- Emerging field: How can teams of agents learn? Individually?  
As groups?
- **Genetic algorithms:**
  - Evolve a society of “fittest” agents
  - In practice: a cool idea that is very hard to make work
- **Strategy learning:**
  - In market environments, learn other agents’ strategies
- **Distributed Reinforcement Learning** (next slide)

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## MAS RL

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- **Distributed Reinforcement Learning**
  - Behave as an individual
  - Receive team feedback
  - Learn to individually contribute to team performance
- How?
  - Iteratively allocate “credit” for group performance to individual decisions

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## Conclusions and Directions

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- Different types of “multi-agent systems”:
  - Cooperative vs. competitive
  - Heterogeneous vs. homogeneous
- Lots of interesting/open research directions:
  - Effective cooperation strategies
  - “Fair” coordination strategies and protocols
  - Learning in MAS
  - Resource-limited MAS (communication, ...)
- Economics: agents are human players with resources