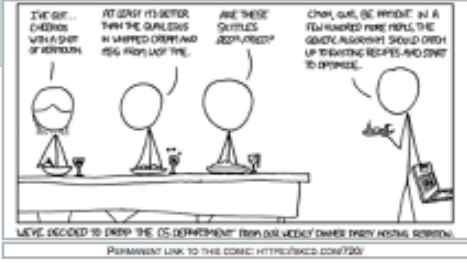


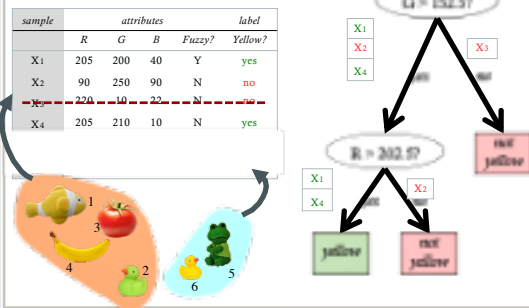
ML II



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One Possible Decision Tree



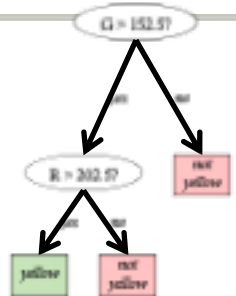
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One Possible Decision Tree

• Predictions

	R	G	B	Fuzzy?	Prediction: Is it yellow?
X7	215	45	190	N	



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Overfitting

- Sometimes, model fits **training data** well but doesn't do well on **test data**
- Can be it "overfit" to the training data
 - Model is too **specific** to training data
 - Doesn't **generalize** to new information well
- Learned model: (YAYAY→B v YANAN→M v ...)

Examples (training data)	Attributes			Outcome
	Bipedal	Flies	Feathers	
Sparrow	Y	Y	Y	B
Monkey	Y	N	N	M
Ostrich	Y	N	Y	B
Bat	Y	Y	N	M
Elephant	N	N	N	M

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Overfitting 2

- Irrelevant attributes → overfitting
- If hypothesis space has many dimensions (many attributes), may find **meaningless regularity**
 - Ex: Name starts with [A-M] → Mammal

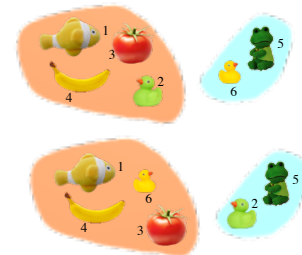
Examples (training data)	Attributes		Class
	Bi-pedal	Feath-ers	
Sparrow	Y	Y	B
Monkey	Y	N	M
Ostrich	Y	Y	B
Bat	Y	N	M
Elephant	N	N	M

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Overfitting 3

- Incomplete training data → overfitting
- Bad training/test split → overfitting



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Overfitting

- Fix by ...
 - Removing irrelevant features (e.g., remove 'first letter' from bird/mammal feature vector)
 - Getting more training data
 - Pruning low nodes in the decision tree (e.g., if improvement from best attribute at a node is below a threshold, stop and make this node a leaf rather than generating child nodes)
- Regularization
- Lots of other choices...

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Noisy Data

- Many kinds of “noise” can occur in the examples:
 - Two examples have same attribute/value pairs, but different classifications
 - Some values of attributes are incorrect
 - Errors in the data acquisition process, the preprocessing phase, //
 - Classification is wrong (e.g., + instead of -) because of some error
 - Some attributes are irrelevant to the decision-making process, e.g., color of a die is irrelevant to its outcome
 - Some attributes are missing (are pangolins bipedal?)

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Pruning Decision Trees

- Replace a whole subtree by a leaf node
- If a **decision rule** establishes that he expected error rate in the subtree is greater than in the single leaf. E.g.,
 - Training: one training red success and two training blue failures
 - Test: three red failures and one blue success
 - Consider replacing this subtree by a single Failure node. (leaf)
- After replacement we will have only two errors instead of five:



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Next Up

- Evaluating a Learned Model
- Elements of a Learning System

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A Learning System

Four components of a machine learning system:

1. **Representation:** how do we describe the problem space?
2. **Actor:** the part of the system that actually does things
3. **Critic:** Provides the experience we learn from
4. **Learner:** the actual learning algorithm

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Representing The Problem

- Representing the problem to be solved is the first decision to be made (and most important)
- Requires understanding the domain – the field in which the problem is set
- There are two aspects of representing a problem:
 1. Behavior that we want to learn
 2. Inputs we will learn from

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Representation: Examples to think about

- How do we describe a problem?
 - Guessing an animal?
 - Playing checkers?
 - Labeling spam email?
 - OCRing a check?
 - Noticing new help desk topics?
- What data do you need to represent for each of these? What model might you learn?

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Representation: Examples

- **Guessing an animal:** a tree of questions and answers
- **Playing checkers:** board, piece positions, rules; weights for legal moves.
- **Labeling spam email:** the frequencies of words used in this email and in our entire mailbox; Naive Bayes.
- **OCRing:** matrix of light/dark pixels; % light pixels; # straight lines, etc.; neural net.
- **Noticing new help desk topics:** Clustering algorithms

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Actor

- Want a system to **do** something.
 - Make a prediction
 - Sort into categories
 - Look for similarities
- Once a model has been learned, we keep using this piece

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How Does the Actor Act?

- **Guessing an animal:** walk the tree, ask the questions
- **Playing checkers:** look through rules and weights to identify a move
- **Identifying spam:** examine the set of features, calculate the probability of spam
- **OCRing a check:** input the features for a digit, output probability for each of 0 through 9
- **Help desk topics:** output a representation of clusters

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Critic

- Provides the experience we learn from
- Typically a set of examples + action that should be taken
- But, can be **any kind** of feedback that indicates how close we are to where we want to be
- Feedback may be after one action, or a sequence

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Critic: Think About

- How do we judge correct actions?
 - **Guessing an animal:**
 - **OCRing digits:**
 - **Identifying spam:**
 - **Playing checkers:**
 - **Grouping documents:**

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Critic: Possible Answers

- How do we judge correct actions?
 - **Guessing an animal**: Human feedback.
 - **OCRing digits**: Human-categorized training set.
 - **Identifying spam**: Match to a set of human-categorized test documents.
 - **Playing checkers**: Who won?
 - **Grouping documents**: Which are most similar in language or content?
- Can be generally categorized as supervised, unsupervised, reinforcement.

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Learner

- The **learner** is the core of a machine learning system. It will:
 - Examine information provided by the critic
 - Modify the representation to improve performance
 - Repeat until performance is satisfactory, or until it stops improving
- The **learner** component is what people mean when they talk about a machine learning algorithm

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What Does the Learner Do?

- **Guessing an animal**: ask user for a question, add it to the binary tree
- **OCRing digits**: modify importance of different input features
- **Identifying spam**: change words likely to be in spam
- **Playing checkers**: increase chance of using some rules, decrease the chance for others
- **Grouping documents**: find clusters of similar documents

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Information Gain

- Concept: make decisions that increase the homogeneity of the data subsets (for outcomes)
- **Information gain** is based on:
 - **Decrease in entropy**
 - After a dataset is split on an attribute.
 - High homogeneity – e.g., likelihood samples will have the same class (outcome)

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Extensions of the Decision Tree Learning Algorithm

- **Using gain ratios**
- Real-valued data
- Noisy data and overfitting
- Generation of rules
- Setting parameters
- Cross-validation for experimental validation of performance
- C4.5 is an extension of ID3 that accounts for unavailable values, continuous attribute value ranges, pruning of decision trees, rule derivation, and so on

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Using Gain Ratios

- Information gain favors attributes with a **large number of values**
 - If we have an attribute D that has a distinct value for each record, then $Info(D,T)$ is 0, thus $Gain(D,T)$ is maximal
- To compensate, use the following ratio instead of Gain:
 $GainRatio(D,T) = Gain(D,T) / SplitInfo(D,T)$
- $SplitInfo(D,T)$ is the information due to the split of T on the basis of value of categorical attribute D
 $SplitInfo(D,T) = I(|T_1|/|T|, |T_2|/|T|, \dots, |T_m|/|T|)$
where $\{T_1, T_2, \dots, T_m\}$ is the partition of T induced by value of D

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Real-Valued Data

- Select a set of thresholds defining intervals
 - Each interval becomes a discrete value of the attribute
- How?
 - Use simple heuristics...
 - Always divide into quartiles
 - Use domain knowledge...
 - Divide age into infant (0-2), toddler (3 - 5), school-aged (5-8)
 - Or treat this as another learning problem
 - Try a range of ways to discretize the continuous variable and see which yield "better results" w.r.t. some metric
 - E.g., try midpoint between every pair of values

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Measuring Model Quality

- Training error
 - Train on all data; measure error on all data
 - Subject to overfitting (of course we'll make good predictions on the data on which we trained!)
- Regularization
 - Attempt to avoid overfitting
 - Explicitly minimize the complexity of the function while minimizing loss
 - Tradeoff is modeled with a *regularization parameter*

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Measuring Model Quality

- How good is a model?
 - Predictive accuracy
 - False positives / false negatives for a given cutoff threshold
 - Loss function (accounts for cost of different types of errors)
 - Area under the curve
 - Minimizing loss can lead to problems with overfitting

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Cross-Validation

- Holdout cross-validation:
 - Divide data into training set and test set
 - Train on training set; measure error on test set
 - Better than training error, since we are measuring *generalization to new data*
 - To get a good estimate, we need a reasonably large test set
 - But this gives less data to train on, reducing our model quality!

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Cross-Validation, cont.

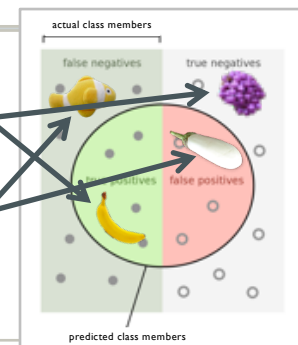
- k-fold cross-validation:
 - Divide data into k folds
 - Train on $k-1$ folds, use the k th fold to measure error
 - Repeat k times; use average error to measure generalization accuracy
 - Statistically valid and gives good accuracy estimates
- Leave-one-out cross-validation (LOOCV)
 - k -fold cross validation where $k=N$ (test data = 1 instance!)
 - Quite accurate, but also quite expensive, since it requires building N models

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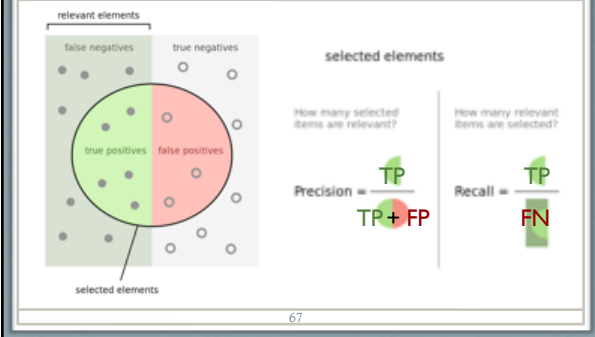
Correctness

- True positive
 - I predict it's yellow and it is yellow
- True negative
 - I predict it's not yellow, and it's not
- False positive
 - I predict it's yellow, but it's not
- False negative
 - I predict it's not yellow, but it is



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Precision/Recall



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