# **Chapter 5.** Adaptive Resonance Theory (ART)

- ART1: for binary patterns; ART2: for continuous patterns
- Motivations: Previous methods have the following problem:
  - 1. Training is non-incremental:
    - with a fixed set of samples,
    - adding new samples often requires re-train the network with the enlarged training set until a new stable state is reached.
  - 2. Number of class nodes is pre-determined and fixed.
    - Under- and over- classification may result from training
    - No way to add a new class node (unless these is a free class node happens to be close to the new input).
    - Any new input x has to be classified into one of an existing classes (causing one to win), no matter how far away x is from the winner. no control of the degree of similarity.

- Ideas of ART model:
  - suppose the input samples have been appropriately classified into k clusters (say by competitive learning).
  - each weight vector  $W_{\cdot j}$  is a representative (average) of all samples in that cluster.
  - when a new input vector  $\boldsymbol{x}$  arrives

1. Find the winner j among all k cluster nodes

2.Compare  $W_{\bullet i}$  with x

if they are sufficiently similar (x resonates with class j),

then update  $W_{\bullet i}$  based on  $x - W_{\bullet j}$ 

else, find/create a free class node and make x as its

first member.

- To achieve these, we need:
  - a mechanism for testing and determining similarity.
  - a control for finding/creating new class nodes.
  - need to have all operations implemented by units of local computation.

#### **ART1** Architecture



 $F_1(a)$ : input units  $F(b)_1$ : interface units  $F_2$ : cluster units  $F_1(a)$  to  $F_1(b)$ : pair - wise connection between  $F_2$  and  $F_1(b)$ : full connection

- $b_{ij}$ : bottom up weights from  $x_i$  to  $y_j$  (real value)
- $t_{ji}$ : top down weights

from  $y_j$  to  $x_i$  (representing class j binary/bipolar)

R, G1, G2 : control units

- $F_2$  cluster units: competitive, receive input vector x through weights b: to determine winner j.
- $F_1(a)$  input units: placeholder or external inputs
- $F_1(b)$  interface units:
  - pass s to x as input vector for classification by  $F_2$
  - compare x and  $t_{i}$  (projection from winner  $y_i$ )
  - controlled by gain control unit G1
- Nodes in both  $F_1(b)$  and  $F_2$  obey 2/3 rule (output 1 if two of the three inputs are 1)  $G_1$

Input to  $F_1(b)$ :  $s_i$ , G1,  $t_{ji}$  Input to  $F_2$ :  $t_{ji}$ , G2, R

• Needs to sequence the three phases (by control units *G1*, *G2*, and *R*)

$$G_{1} = \begin{cases} 1 & \text{if } s \neq 0 \text{ and } y = 0 \\ 0 & \text{otherwise} \end{cases}$$

$$G_{1} = 1: \quad F_{1}(b) \text{ open to receive } s \neq 0$$

$$G_{1} = 0: \quad F_{1}(b) \text{ open for } t_{J}.$$

$$G_{2} = \begin{cases} 1 & \text{if } s \neq 0 \\ 0 & \text{otherwise} \end{cases}$$

$$G_{2} = 1 \text{ signals the start of a new classification for a new input}$$

$$R = \begin{cases} 0 & \text{if } \frac{\|x\|}{\|s\|} \ge r \end{cases}$$

1 otherwise

o < r < 1 vigilance parameter

R = 0: resonance occurs, update  $b_{\bullet J}$  and  $t_{J \bullet}$ 

 $\mathbf{R} = 1$ : fails similarity test, inhibits  $\mathbf{J}$  from further computation

## Working of ART1

- Initial state: nodes on  $F_1(b)$  and  $F_2$  set to zeros
- *Recognition phase*: determine the winner cluster for input *s*

 $s \neq 0$  is applied to  $F_1(a)$  and stay there (clamped)  $G_1 = 1$  (:  $y = 0, s \neq 0$ )  $G_2 = 1$  (:  $s \neq 0$ )  $F_1(b)$  is open to receive s R = 0 (|x|/|s| = 1 > r)  $F_2$  is open to receive  $x \cdot b_{\cdot j}$ determine winner Jx is tentatively classified to cluster J

$$\boldsymbol{Y}_J = 1 \quad \boldsymbol{Y}_{k \neq J} = 0$$

• Comparison phase:  $t_{I_{\bullet}}$  is sent down from  $F_{2}$  $G_1 = 0 \quad (\mathbf{y} \neq 0)$ new **x** appears on  $F_1(b)$ :  $x_i = s_i \wedge t_{Ji}$  (2/3 rule) if  $||x|| / ||s|| \ge \mathbf{r} \quad \mathbf{R} = 0$ a resonance occurs, the classification is accepted if  $||x|| / ||s|| < \mathbf{r}$  R = 1classification is rejected reset signal is sent (from  $\boldsymbol{R}$  to  $\boldsymbol{F}_2$ )  $y_I$  is permanently disabled all other  $y_k$  is set to zero goes back to recognition phase search for other possible match

#### • Weight update/adaptive phase

- Initial weight: (no bias) bottom up:  $0 < b_{ij}(0) < L/(L-1+n)$  (*L* usually 2) top down:  $t_{ji}(0) = 1$
- When a resonance occurs with  $y_J$ , update  $b_{\bullet J}$  and  $t_{J \bullet}$ s : current input (on  $F_1(a)$ )
  - x : comparison result between s and  $t_{J\bullet}$  (on  $F_1(b)$ )

$$x_{i} = s_{i} \cdot t_{Ji}$$
  
new  $t_{Ji} = x_{i}$  new  $b_{ij} = \frac{Lx_{i}}{L - 1 + ||x||}$ 

- If k sample patterns are clustered to node  $y_{J}$  then  $t_{\bullet J} =$  pattern whose 1's are common to all these k samples  $t_{\bullet J} = s(1) \land s(2) \dots s(k)$   $b_{\bullet J} (\text{new}) \neq 0 \text{ iff } x_i \neq 0 \text{ only if } s_i \neq 0$  $t_{J \bullet} = x, b_{\bullet J} \text{ is a normalized } t_{\bullet J}$  – Winner may shift:

$$L = 2, b_{ij}(0) = 0.2$$
  

$$s(1) = (1 \ 1 \ 1 \ 0) \qquad t_{1 \bullet} = (1 \ 1 \ 1 \ 0)$$
  

$$s(2) = (1 \ 1 \ 0 \ 0) \qquad t_{1 \bullet} = (1 \ 1 \ 0 \ 0)$$
  

$$s(3) = (1 \ 0 \ 0 \ 0) \qquad t_{1 \bullet} = (1 \ 0 \ 0 \ 0)$$
  

$$s(1) = (1 \ 1 \ 1 \ 0) \qquad \frac{\|x\|}{\|s\|} = \frac{1}{3} < \mathbf{r}$$

- What to do when failed to classify into any existing cluster?
  - report failure/treat as outlier
  - add a new cluster node  $y_{m+1}$  with

$$b_{i,m+1} = \frac{L}{L-1+n}, t_{m+1,i} = 1$$

## Notes

- 1. Classification as a search process
- 2. No two classes have the same *b* and *t*
- 3. Different ordering of sample input presentations may result in different classification.
- 4. Increase of  $\rho$  increases # of classes learned, and decreases the average class size.
- 5. Classification may shift during search, will reach stability eventually.
- 6. ART2 is the same in spirit but different in details.