EDA

Electronic design automation (EDA) is the practice of using computer-based software systems to design VLSI circuits.

Many tools exist within EDA -- we focus here on the *hardware description languages* (HDL), in particular **Verilog**.

HDLs enable designers to write computer-based descriptions of the properties, signals and functionality of a circuit.

Traditional approach for the designer is to work at the gate or transistor level.

Today, designers *capture* their designs in software, at higher levels of abstraction.

This methodology is coupled with *synthesis tools* to translate and optimize the description of the design.

Synthesis engines map the design to physical parts such as an ASIC or FPGA.



EDA

Despite the powerful features available in such an approach, HDLs have not been widely accepted because:

- Many designs are of a size and complexity that allow schematic entry to be used successfully.
- Many engineers lack a working familiarity with HDLs.

Design flow

Design specifications summarize the **functional behavior**, **timing requirements**, and other relevant attributes including *speed*, *power* and *area*.

Design entry is the process of encapsulating a representation of the design, i.e., schematic, state transition diagrams, HDL, etc.

Each step in the *design flow* either:

- Creates a database supporting the design flow
- Verifies that the design meets specific criteria

A design flow starts with *design entry* and ends with photomasks.



Design Flow

A successful design might require multiple, iterative passes through all or part of this flow

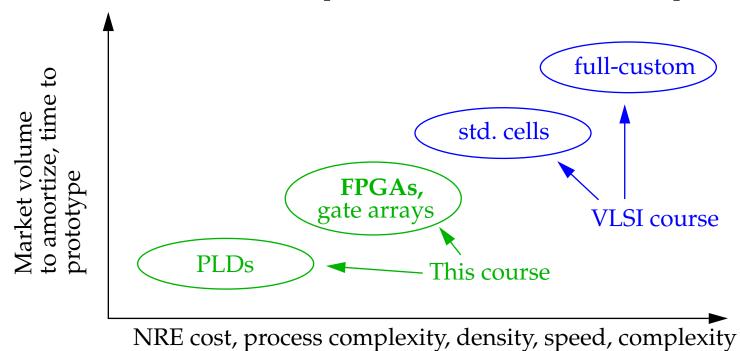
First design flow Create gate-level desc. ↓ (consider testability) Verify/Simulate ↓ (generate test patterns) Verify timing ↓ Create masks DRC/extract parasitics



Design Flow

There are several physical realizations of the design in hardware.

Each offers trade-offs with respect to time-to-market, cost, and performance.



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Design Entry

As indicated, **design entry** encapsulates a description of the design in a database that serves subsequent steps in the design fl ow

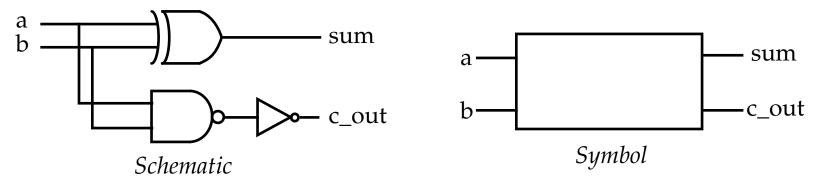
Schematics and *HDLs* are the two commonly used modes of entry.

Schematic entry focuses on the structural detail of the design.

Advantages: Familiarity of the designer with this *visual format* Disadv: Supports only a low to moderate level of circuit complexity.

Almost all CAD tools support this mode of design entry, many with fancy graphical interfaces and verification tools.

Divide and conquer through *hierarchical decomposition* is extensively used.





Design Entry

A **HDL** is a programming language with special constructs and semantics to *model*, *represent*, and *simulate* the function and timing of the hardware.

Variables are used to represent electrical signals.

Their semantics include both a value and time.

This allows the *temporal* relationship of the signals to be described, generated and manipulated.

Tools exist that convert the HDL text to schematic automatically.

HDLs allow the designer to describe the design as a *structural entity* (such as that required by schematic).

HDLs also allow the designer to describe the design as a *behavioral entity*, using procedural code.

This decouples the description of the design from actual physical hardware.



Structural Verilog

The Verilog HDL counterpart of the schematic shown earlier:

Module Ports can be **inout** for bidirectional signals

Gates are instantiated in the body of the module.

IMPORTANT: The order of the statements within the module is **inconsequential** -- signal values and assignments are functions of time! In programming languages such as C, order does matter.



Behavioral Verilog

As indicated, Verilog also allows behavioral descriptions of designs:

```
module flip_flop (q, data_in, clk, rst);
input data_in, clk, rst;
output q;
reg q;

always @ (posedge clk)
begin
if (rst == 1) q = 0;
else q = data_in;
end
endmodule
Declares q to be a register value,
i.e., it retains its value once
it is assigned between clk edges.
reg is an abstract memory variable
endmodule
```

Here, execution halts at the **always** statement until *clk* has a rising edge.

When this occurs, the body executes, which assigns *q* the value *data_in* unless *rst* is asserted.

Once executed, execution is halted once again at the *always* statement until the next *event* (*clk* has a rising edge) occurs.

Behavioral Verilog

The previous code is *event-controlled*.

The event control statement (*always* @...) defines the sensitivity of the behavioral model to external signals.

IMPORTANT: The order within the *process* block execute **sequentially**, just like they do within C (subject to any timing control expressions).

Within Verilog, there are 3 types of timing controls:

- Event control
- Delay control
- The wait statement

The first 2 are intuitive, event control suspends execution until an event occurs, while delay control suspends execution for a specified time.

The **wait** statement suspends execution until a condition is satisfied (more on this later).

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Behavioral Verilog

A more complex behavioral model:

The **assign** statement describes a behavior (addition) that requires several gates in actual hardware.

The keyword **assign** and the '+' operator provide a *shortcut*, i.e., they describe the behavior of the circuit without a physical representation.

This style of Verilog is referred to as *register transfer level* (**RTL**) because it represents operations on a data path conveniently using operators.