

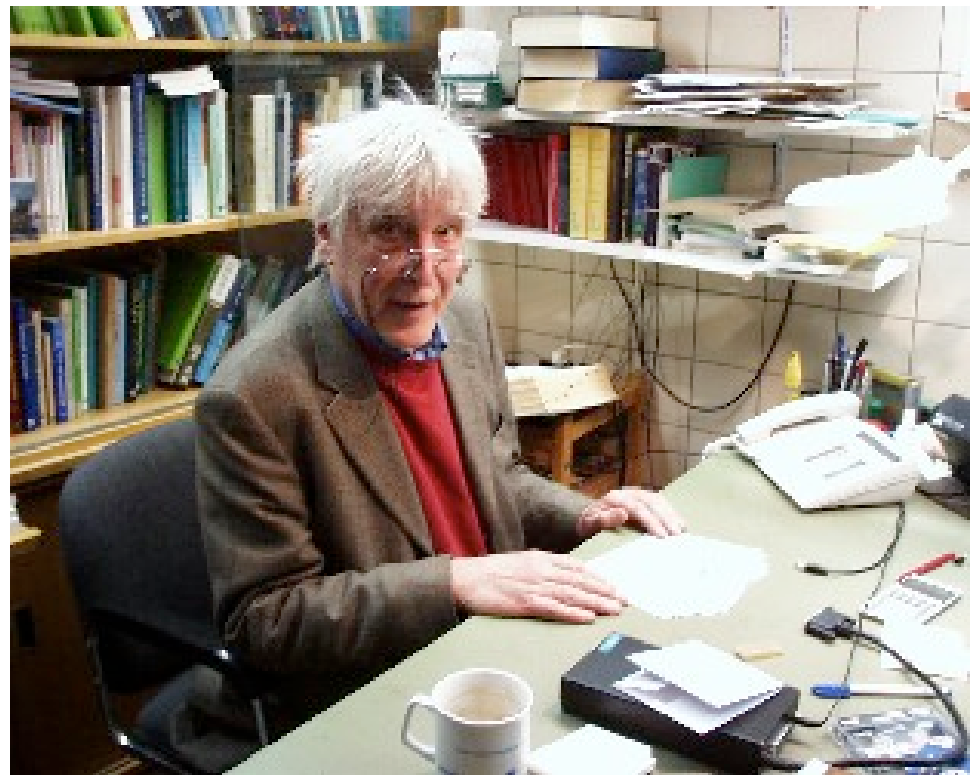
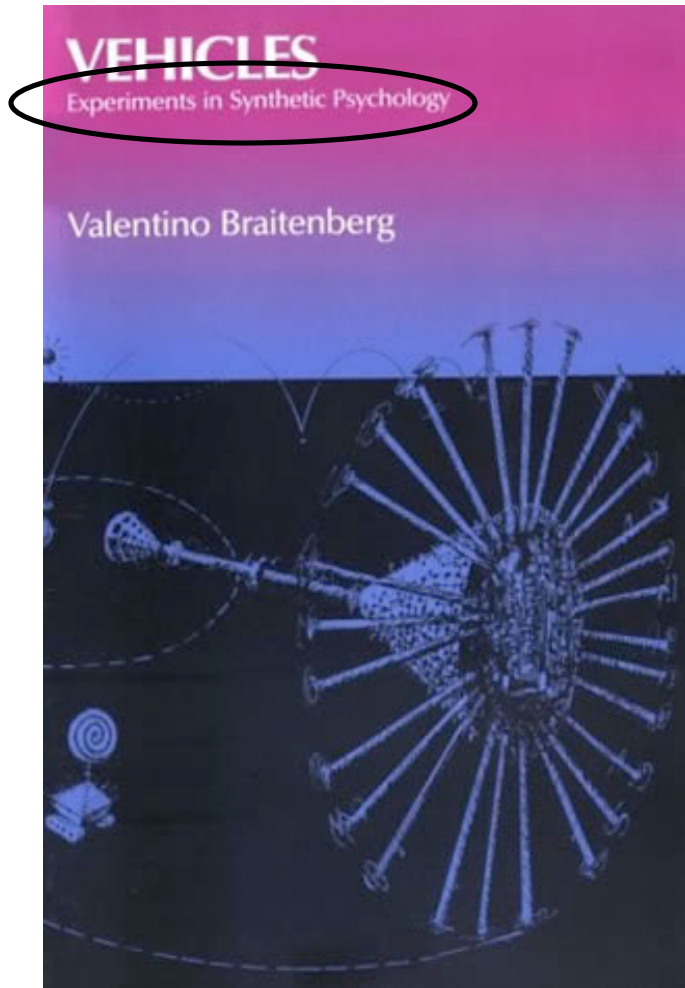
# Motors and Motor Control

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- Braitenberg's Vehicles
- Circuits 101
  - Some things the CMPEs know and the CMSCs are afraid to ask
- Physics 101
  - Some things we all knew at one time but forgot
- Motors 101
  - Pre-reqs Circuits 101 and Physics 101
  - Motors 101 Lab
- Motors 201
  - Servos and servo control

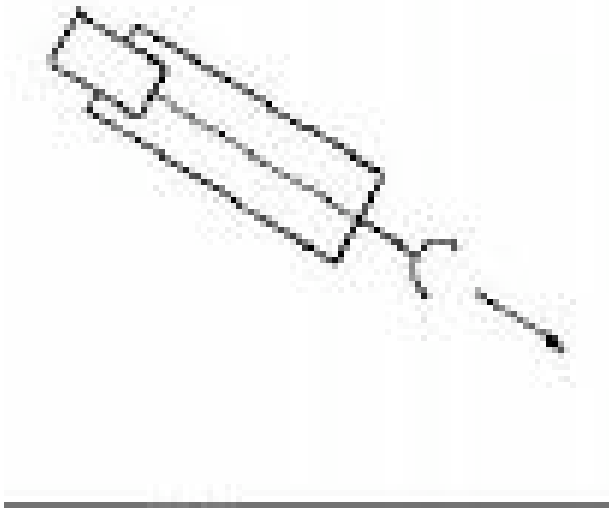
# Braitenberg's Vehicles

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# Alive!

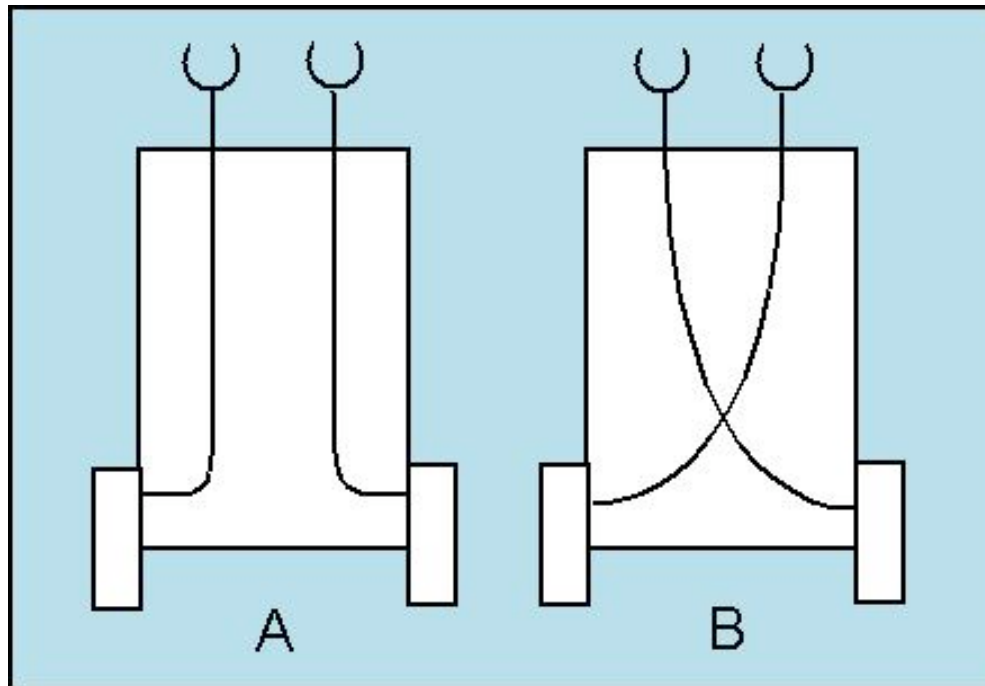
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- One sensor
- One drive wheel
- Excitatory connection
- Behavior?

# Variants

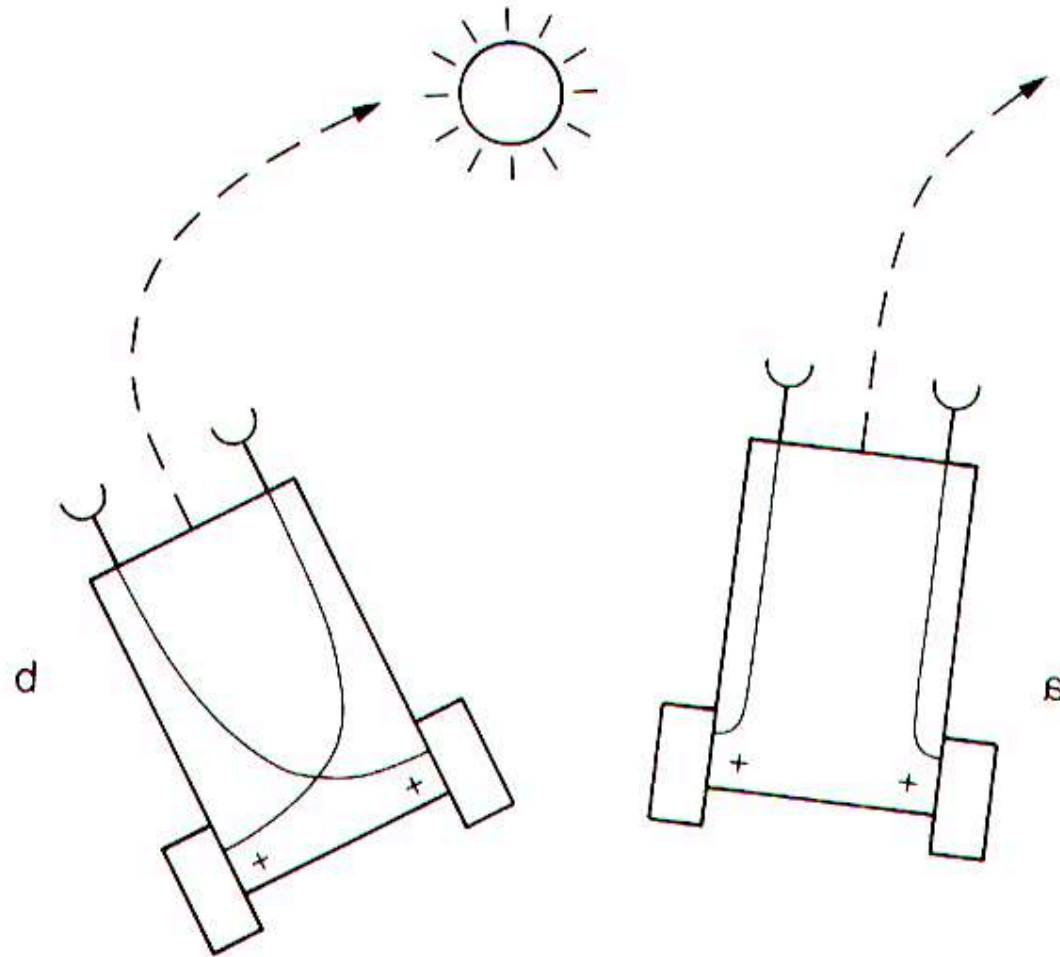
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- More wheels
- More sensors
- Crossed connections

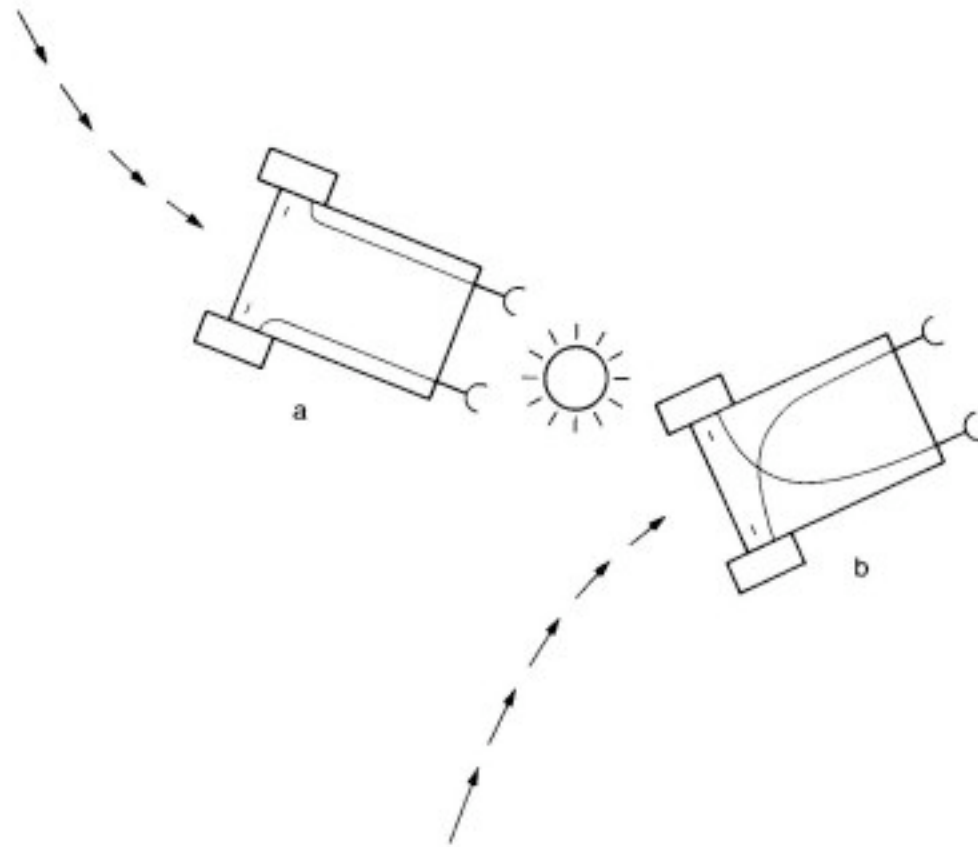
# Fear and Aggression - Excitatory Links

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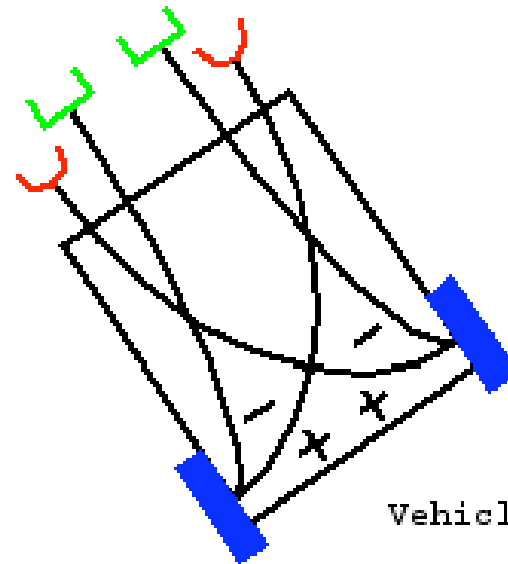
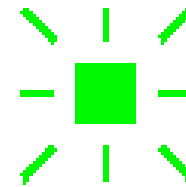
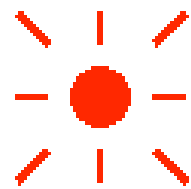
# Love - Inhibitory Links

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# More Complexity: What does this one do?

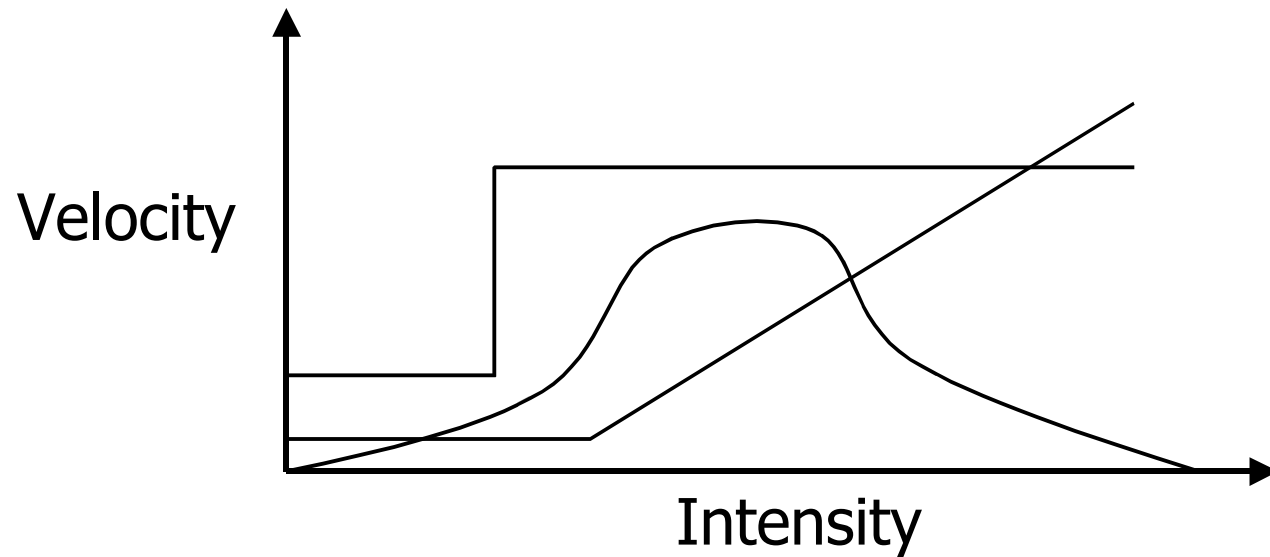
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Vehicle 3

# Special Tastes

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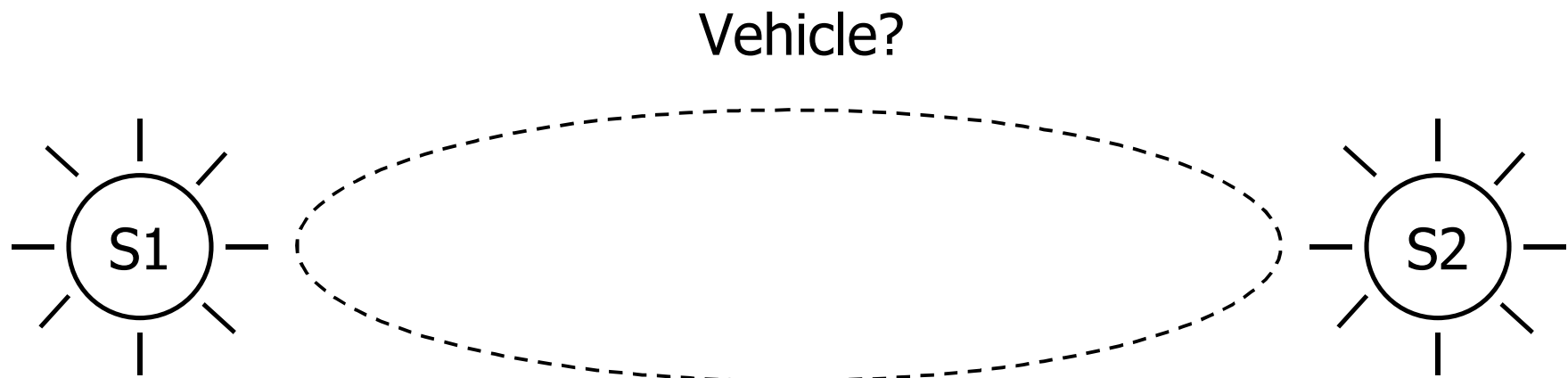


- Non-linear relationship between intensity and velocity
- Behaviors?



# Exercise

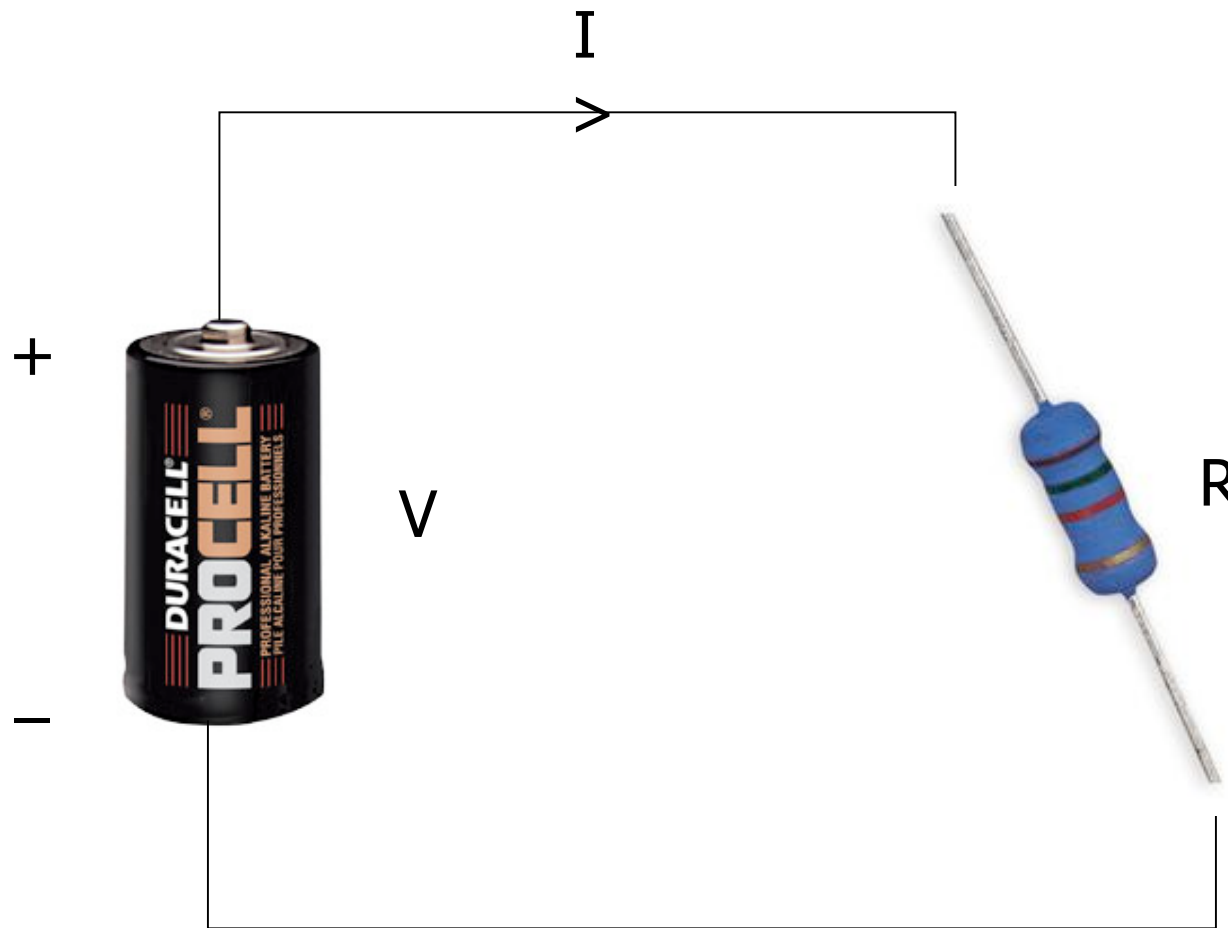
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- Design a vehicle that behaves as shown above
- How many sensors and wheels?
- Connections and activation profile?

# Circuits 101

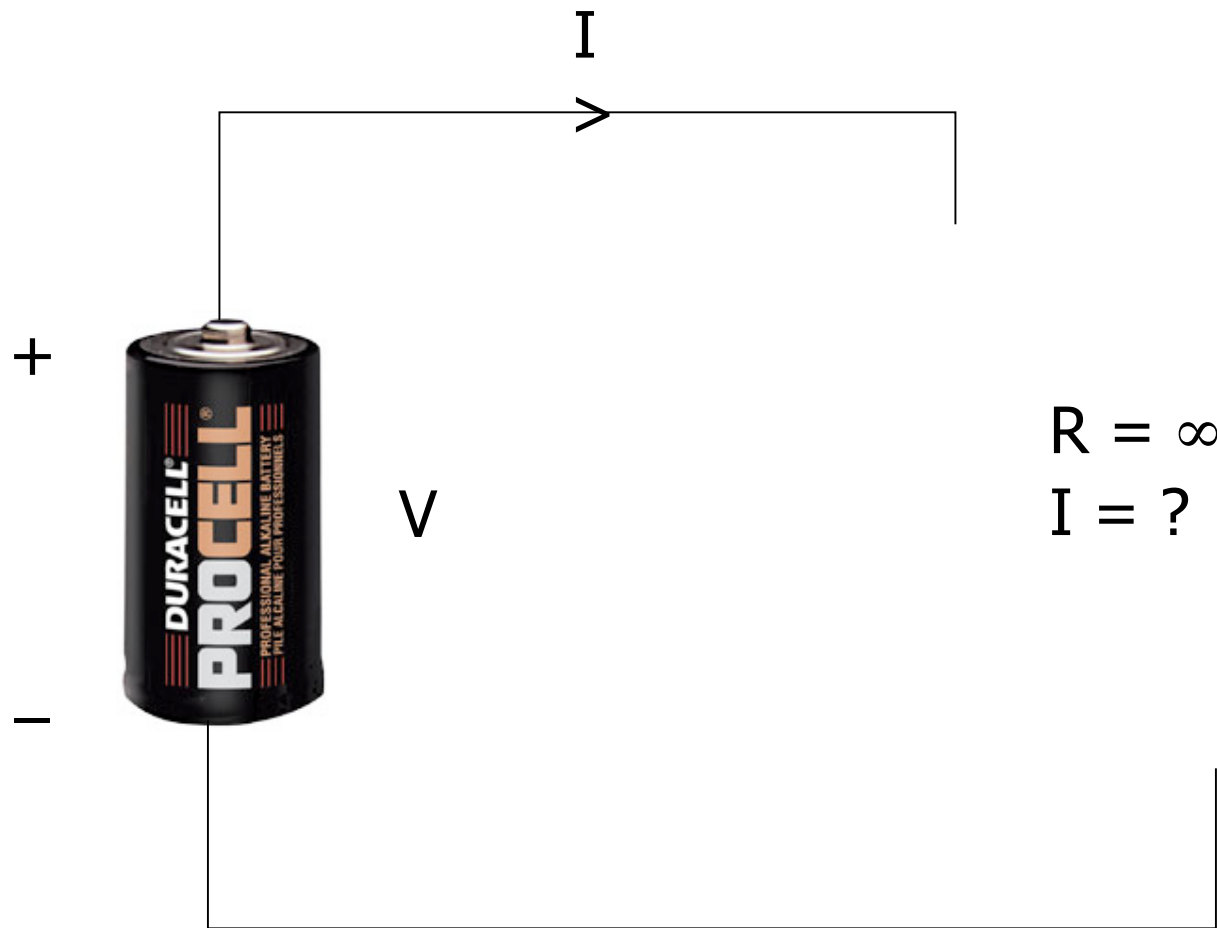
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- $V = I R$
- $I = V / R$
- $R = V / I$

# Circuits 101

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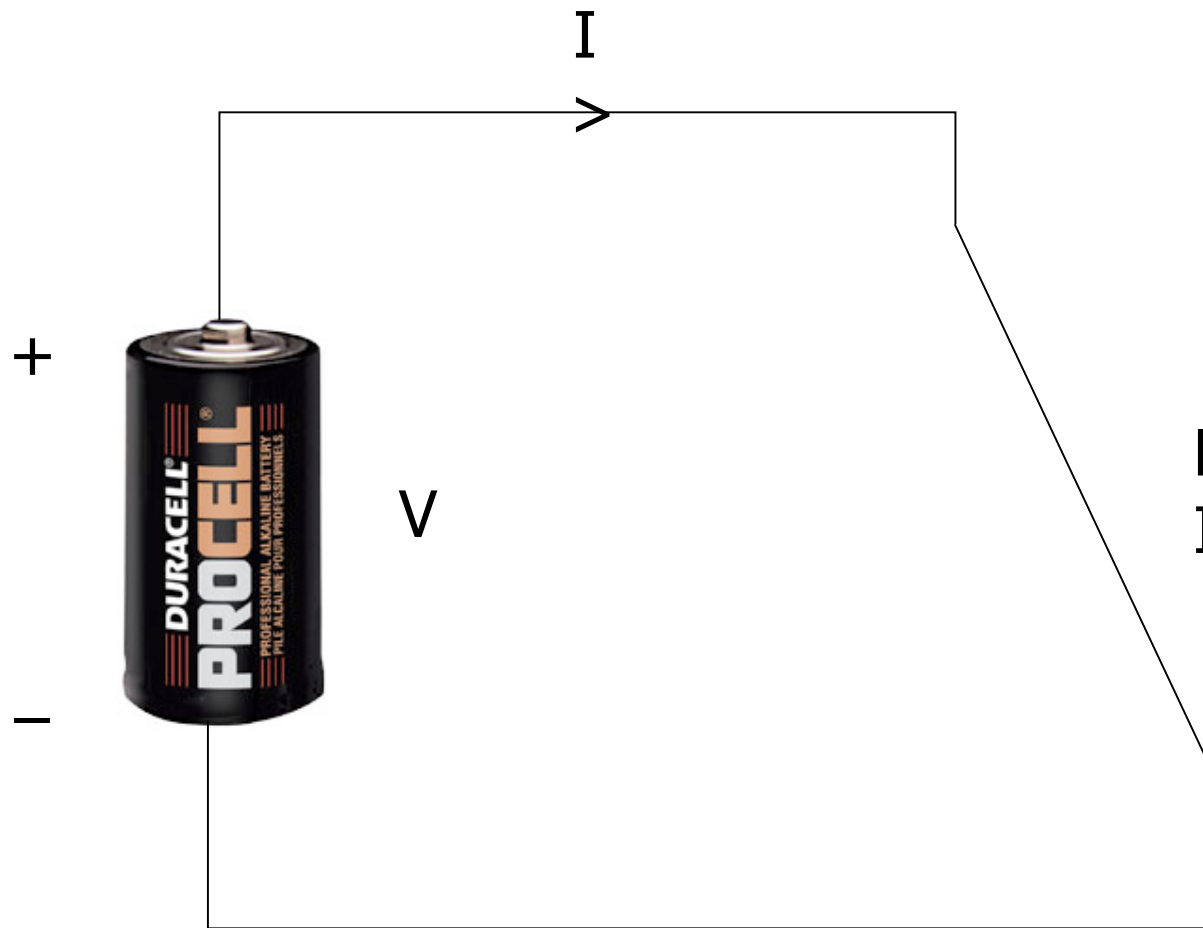


- $V = I R$
- $I = V / R$
- $R = V / I$

$$R = \infty$$
$$I = ?$$

# Circuits 101

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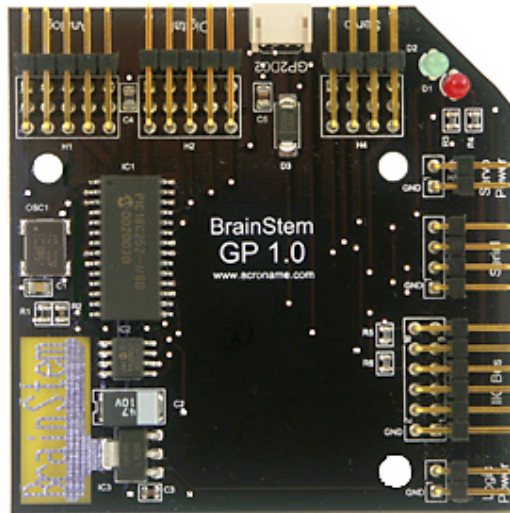


- $V = IR$
- $I = V / R$
- $R = V / I$

$$R = 0$$
$$I = ?$$

# Microcontrollers

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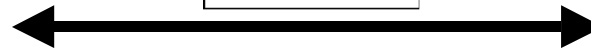
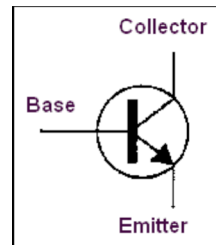
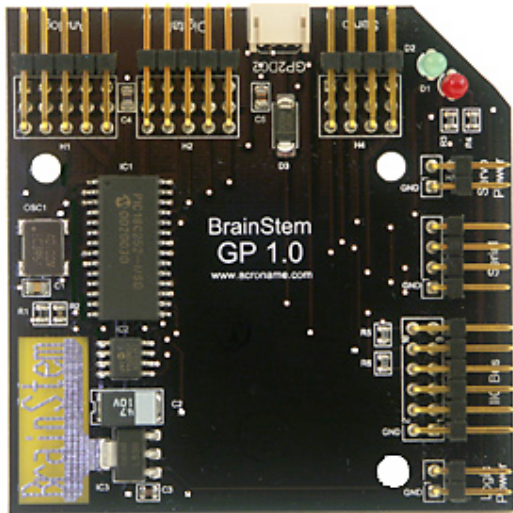


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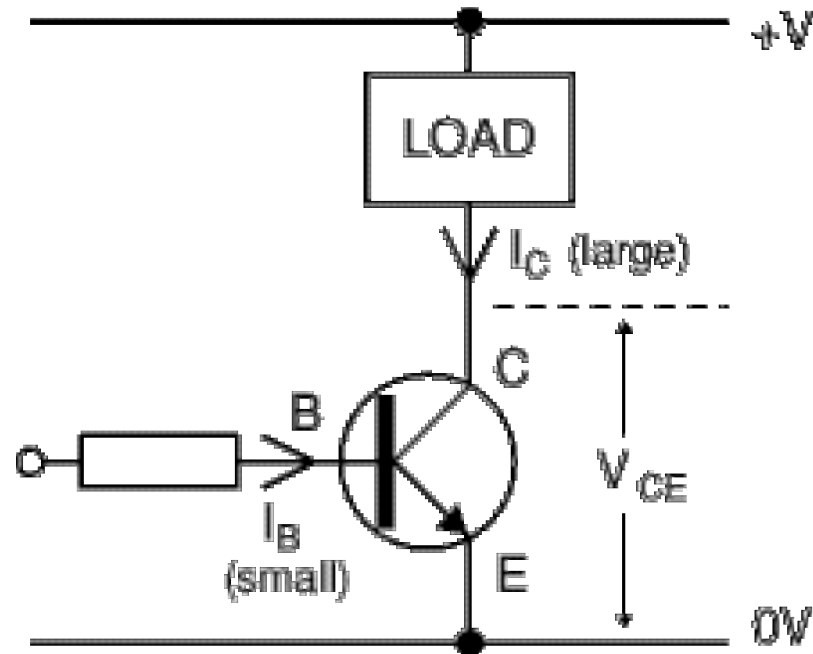
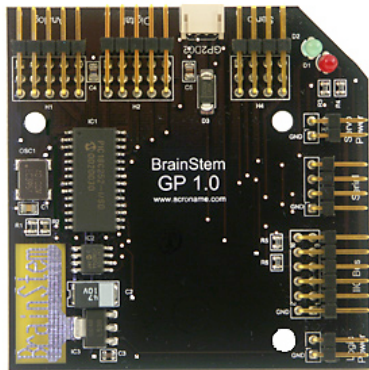
# Microcontrollers

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# Transistors

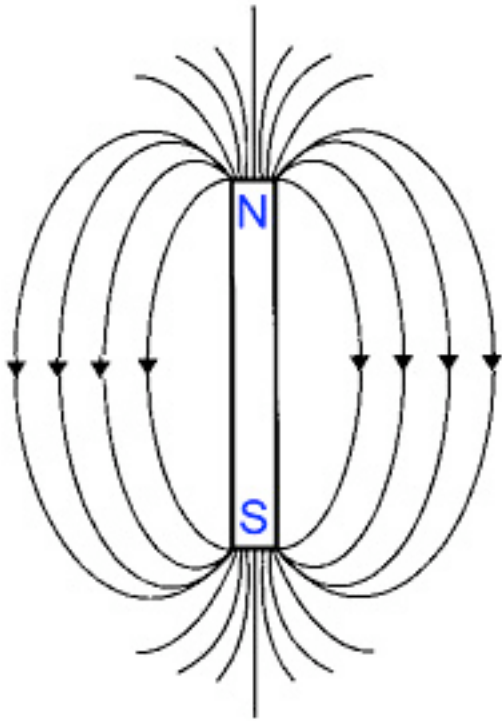
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- Often used as switches
- Small BE current controls much larger CE current

# Physics 101 - Magnets

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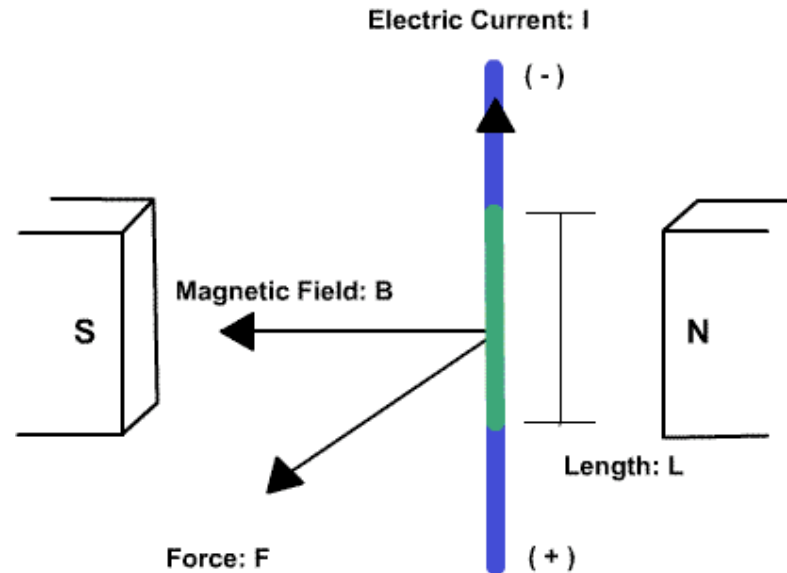


- Two poles - North and South
  - Like poles repel
  - Opposite poles attract
- Magnetic field
  - Flux lines
  - Directed from North to South



# Physics 101 - Lorentz Force

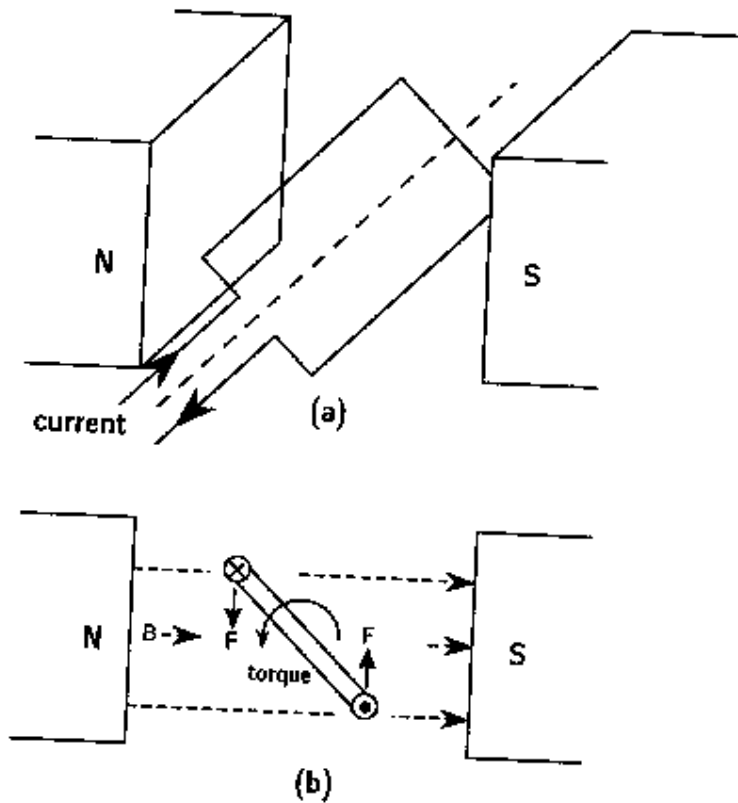
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- Force acts on wire carrying current in magnetic field
- Direction of force from right-hand rule
  - Curl fingers from direction of current flow (+ to -) in direction of flux flow (N to S)
  - Check thumb, it points in direction of force on wire

# Motors 101 - DC Motors

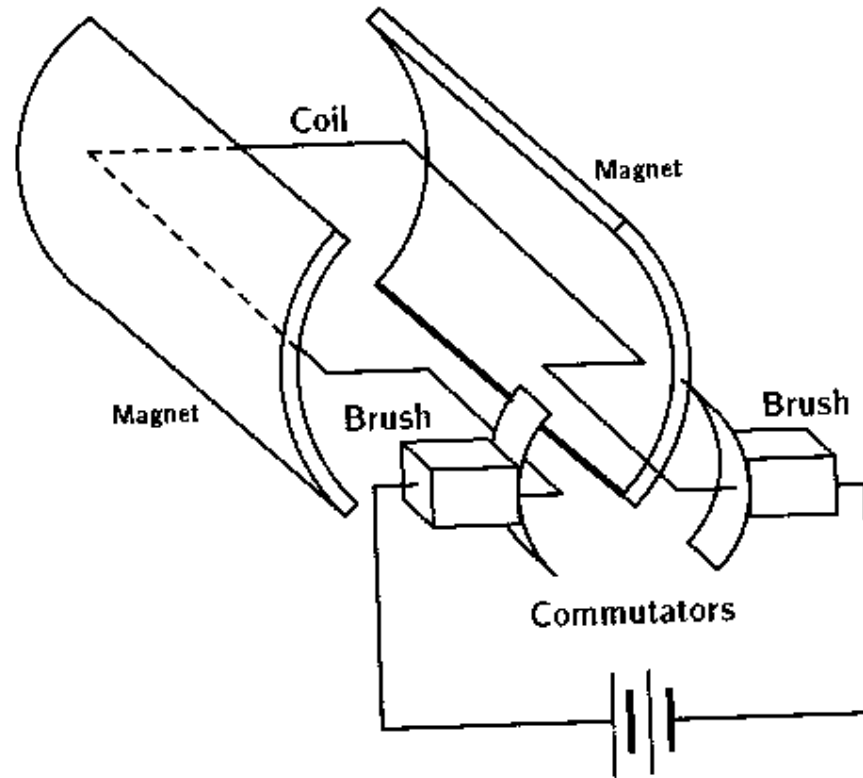
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- What forces are acting on wire?
- How do forces change when wire rotates?

# Motors 101 - Commutation

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# Motors 101 Lab

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- **Build your own motor!!!**
- Form groups of 3
- Read handout and build motor
- Let me know when it's working
- Experiments
  - Flip magnet
  - Flip coil
- Questions
  - How/why does motor work?
  - Which side of the magnet is north?
  - What if you sand both sides of coil?

# Motors 101

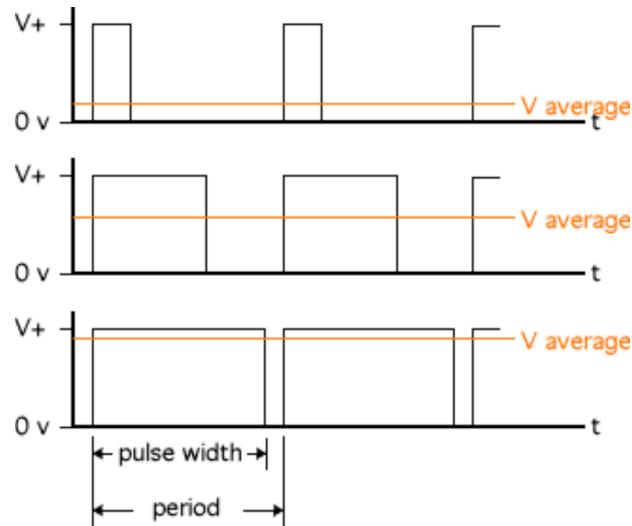
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# Motors 201 - Speed Control

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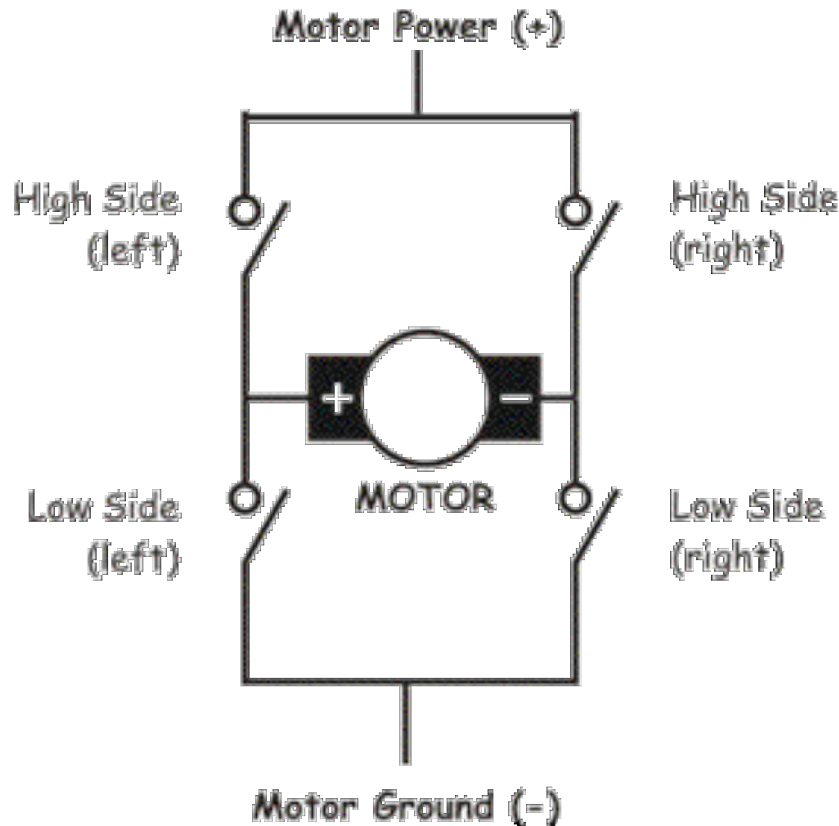


Why not  
reduce voltage  
with a variable  
resistor?

- Turn power on and off quickly
  - Period
  - Pulse width
  - $\text{Pulse width} / \text{Period} = \text{Duty cycle}$
- Longer pulses lead to faster rotation
  - Try it with your lab motors

# Motors 201 - Direction Control

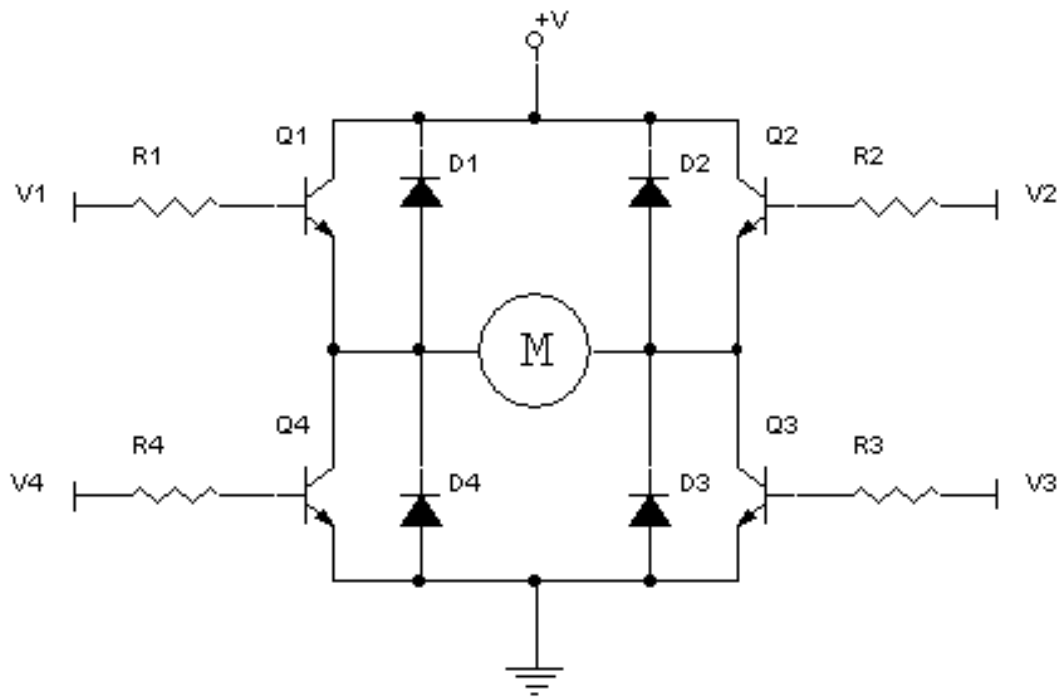
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- H-bridge
- Four switches
- Easily change polarity on motor
- Reverse direction
- Used in conjunction with PWM

# Motors 201 - Direction Control

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- H-bridge
- Four switches
- Easily change polarity on motor
- Reverse direction
- Used in conjunction with PWM



# Motors 201 - Torque

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- Torque
  - Rotational force
  - Linear force times distance
  - Units: oz-in
  - Force required to lift 1oz using 1in radius pulley
- DC Motors
  - High angular velocity
  - Low torque
  - Use gears to flip that relationship so robot can move larger masses more slowly
- DC gearhead motors



# Motors 201 - Motor Specs

---

## SPECS:

Speed: 0.23 sec/60 degrees at 4.8V

0.19 sec/60 degrees at 6.0V

Torque: 44 oz-in (3.2 kg-cm) at 4.8V

57 oz-in (4.1 kg-cm) at 6.0V

Length: 1.6" (41mm)

Width: 0.8" (20mm)

Height: 1.4" (36mm)

Weight: 1.3 ounce (37.2 grams)



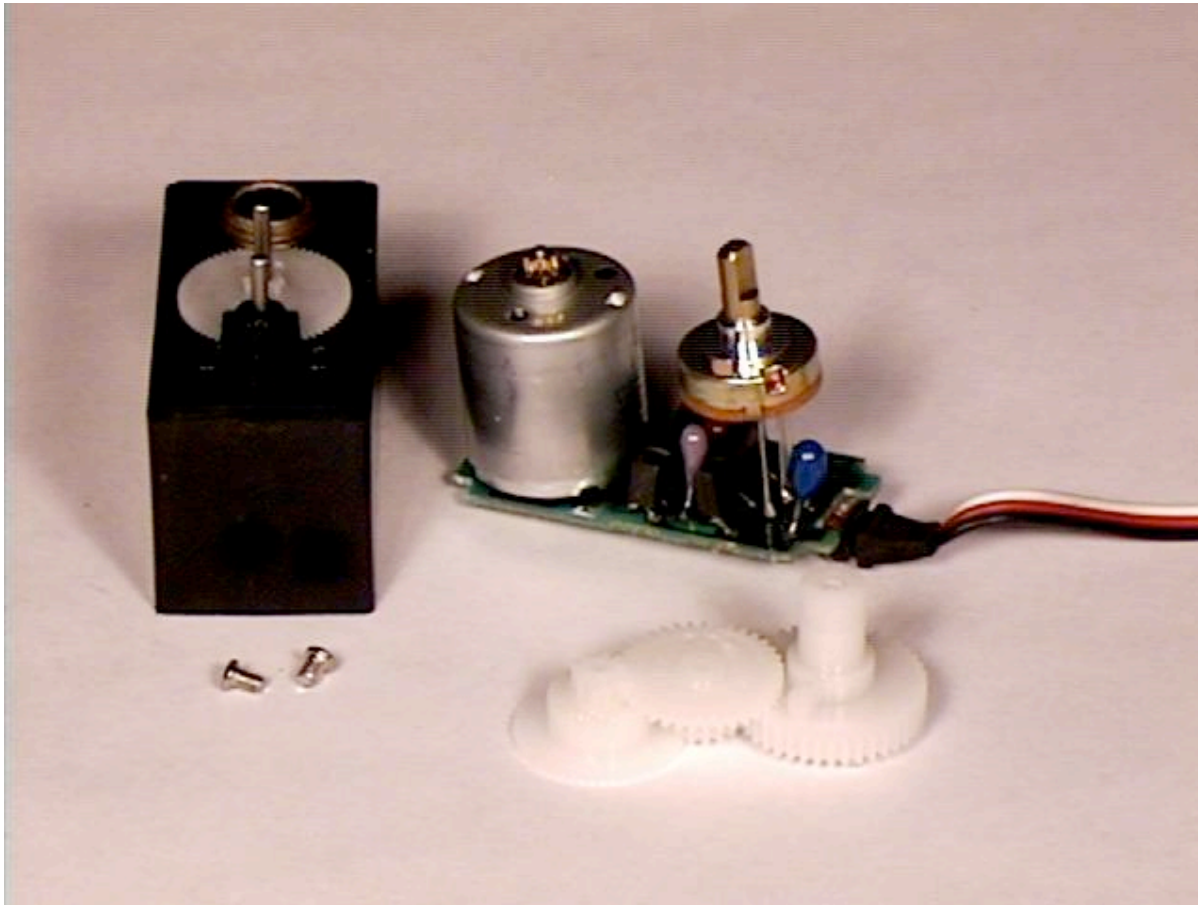
# Motors 201 - Servos

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- DC motor + gears + control circuitry
- Constrained motion - typically 180 degrees
- Set desired rotational position
- Active control to maintain that position
- Applications
  - Robotics - arms, legs
  - RC Airplanes
  - Many others

# Motors 201 - Servos

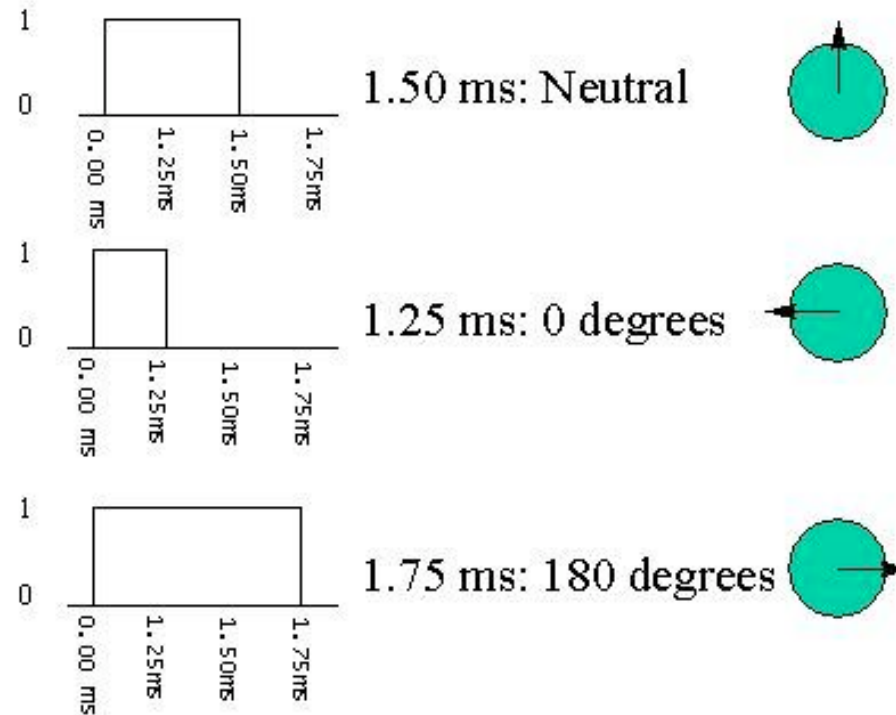
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- DC motor
- Gears (torque)
- Circuit
- Potentiometer
- Control cable
- Hard stop

# Motors 201 - Servo Position Control

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- Pulse width modulation (for a different purpose)
- 20ms period, duty cycle indicates position