

# **CMSC 671**

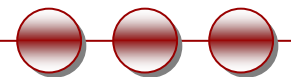
## **Fall 2010**

**Thu 11/09/10**

# **Decision Making Under Uncertainty**

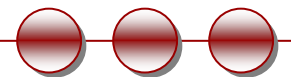
## **Chapter 16**

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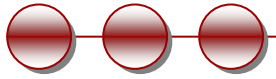


# Decision Making Under Uncertainty

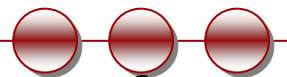
- Decision theoretic agents
  - Combine
    - Probability theory
    - Utility theory
  - Make rational decisions based on
    - what it believes
    - what it wants



# Decision Making Under Uncertainty



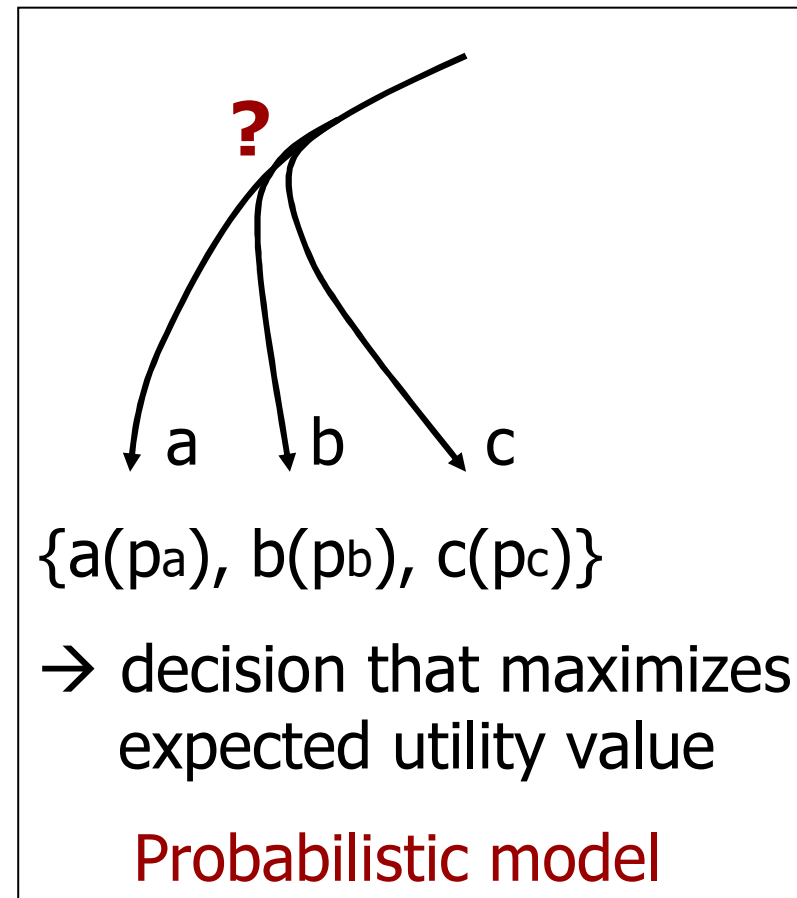
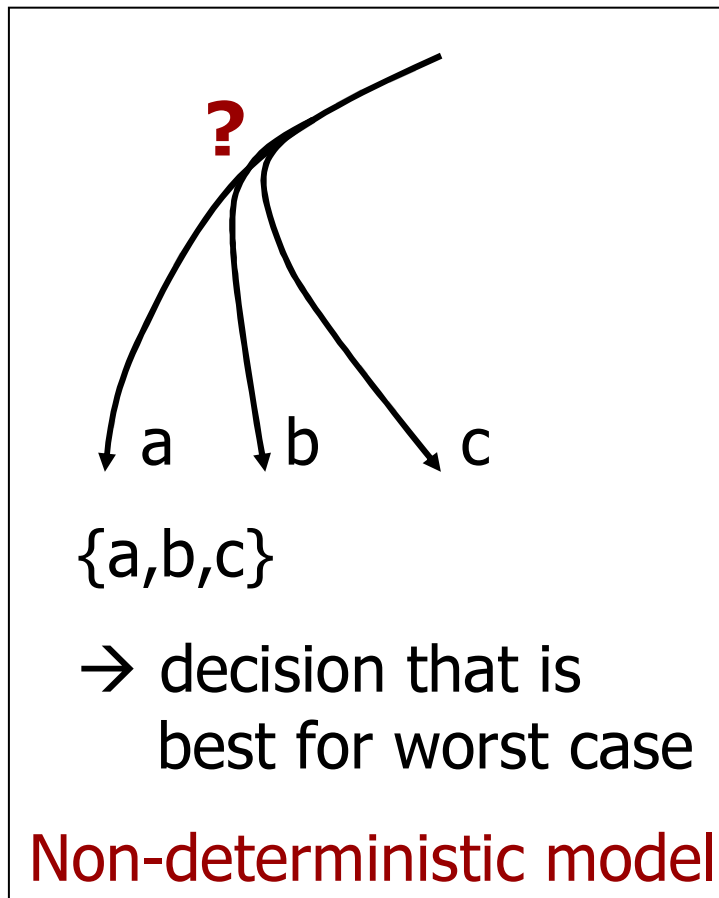
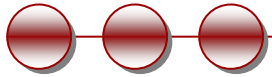
- Many environments have multiple possible outcomes
- Some of these outcomes may be good; others may be bad
- Some may be very likely; others unlikely
- What's a poor agent to do??



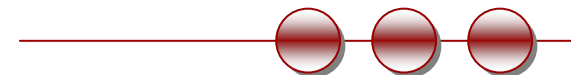
# Probabilistic outcomes

- The probability of outcome  $s'$  given evidence observations  $e$ :
  - $P(\text{Result}(a)=s'|a,e)$
- Desirability of a state (agent's preferences):
  - $U(s)$
- Expected utility of an action given the evidence:
  - $EU(a|e) = \sum_s P(\text{Result}(a)=s'|a,e)U(s')$
- Maximum expected utility:
  - $action = \operatorname{argmax}_a EU(a|e)$

# Non-Deterministic vs. Probabilistic Uncertainty



~ Adversarial search

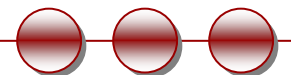




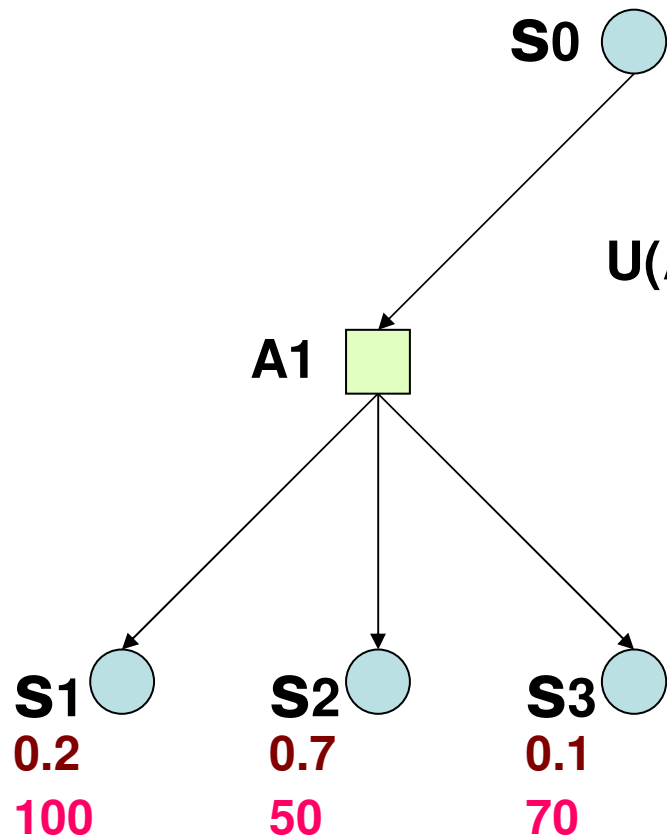
# Expected Utility

- Random variable  $X$  with  $n$  values  $x_1, \dots, x_n$  and distribution  $(p_1, \dots, p_n)$   
E.g.:  $X$  is the state reached after doing an action  $A$  under uncertainty
- Function  $U$  of  $X$   
E.g.,  $U$  is the utility of a state
- The expected utility of  $A$  is

$$EU[A] = \sum_{i=1, \dots, n} p(x_i|A)U(x_i)$$

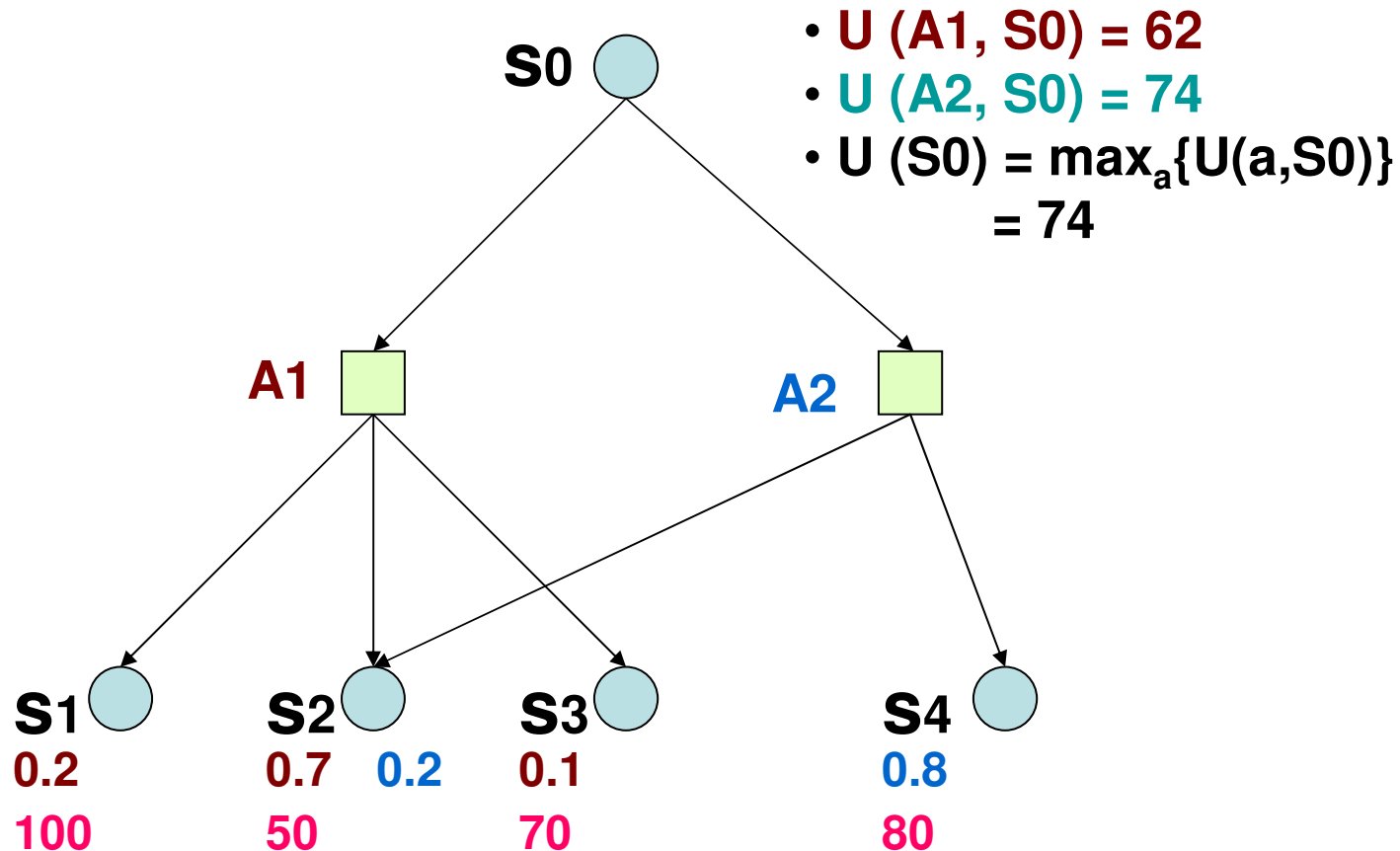


# One State/One Action Example



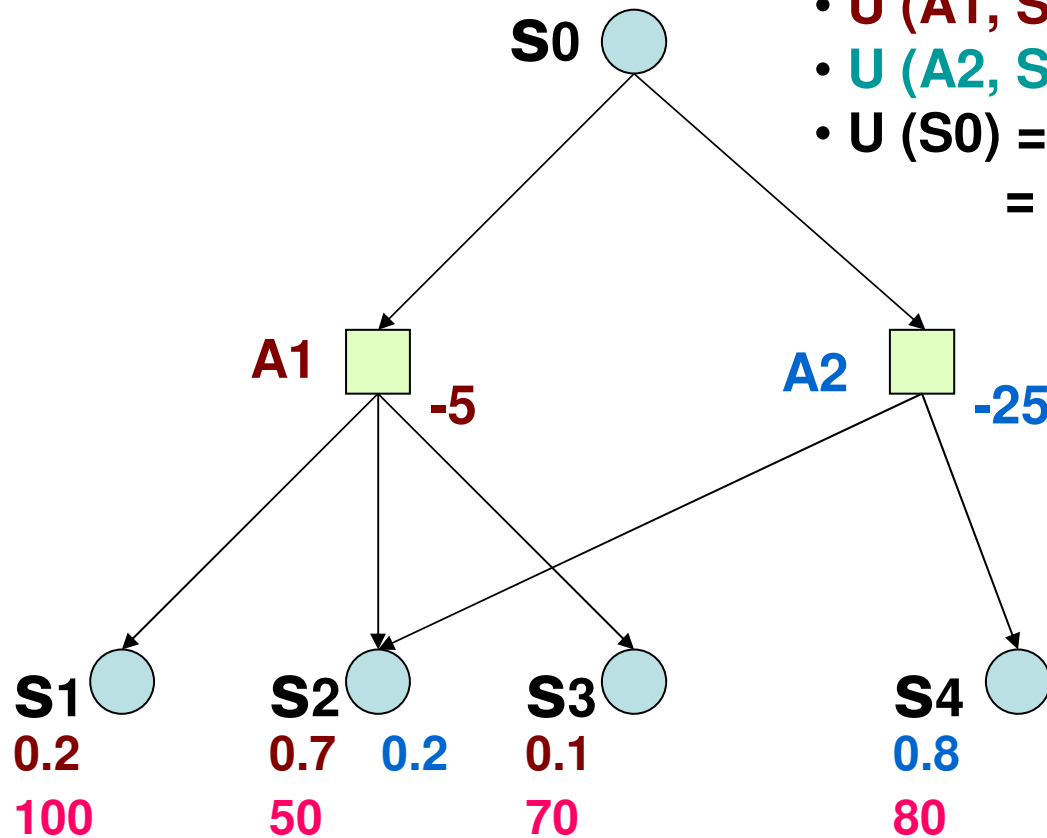
$$\begin{aligned} U(A1, S0) &= 100 \times 0.2 + 50 \times 0.7 + 70 \times 0.1 \\ &= 20 + 35 + 7 \\ &= 62 \end{aligned}$$

# One State/Two Actions Example





# Introducing Action Costs

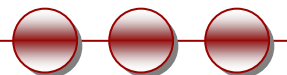


- $U(A_1, S_0) = 62 - 5 = 57$
- $U(A_2, S_0) = 74 - 25 = 49$
- $U(S_0) = \max_a \{U(a, S_0)\} = 57$



# MEU Principle

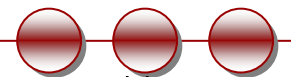
- A **rational agent** should choose the action that maximizes agent's expected utility
  - This is the basis of the field of **decision theory**
  - The MEU principle provides a **normative criterion** for rational choice of action
- 
- AI is solved!!!





# Not quite...

- Must have a **complete** model of:
  - Actions
  - Utilities
  - States
- Even if you have a complete model, decision making is computationally **intractable**
- In fact, a truly rational agent takes into account the utility of reasoning as well (**bounded rationality**)
- Nevertheless, great progress has been made in this area recently, and we are able to solve much more complex decision-theoretic problems than ever before





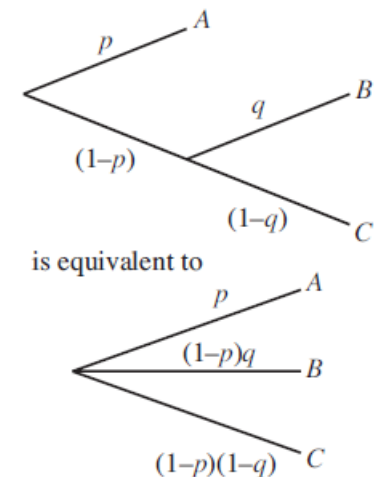
# Agent preferences (notation)

- $A > B$ 
  - The agent prefers A over B
- $A \sim B$ 
  - The agent is indifferent between A and B
- $A > \sim B$ 
  - The agent prefers A over B or is indifferent between them



# Axioms of Utility Theory

- Orderability
  - $(A > B) \vee (A < B) \vee (A \sim B)$
- Transitivity
  - $(A > B) \wedge (B > C) \Rightarrow (A > C)$
- Continuity
  - $A > B > C \Rightarrow \exists p [p, A; 1-p, C] \sim B$
- Substitutability
  - $A \sim B \Rightarrow [p, A; 1-p, C] \sim [p, B; 1-p, C]$
- Monotonicity
  - $A > B \Rightarrow (p \geq q \Leftrightarrow [p, A; 1-p, B] > \sim [q, A; 1-q, B])$
  - Also for  $A \sim B$
- Decomposability
  - $[p, A; 1-p, [q, B; 1-q, C]] \sim [p, A; (1-p)q, B; (1-p)(1-q), C]$
  - (figure above)



# Value Function

- Provides a ranking of alternatives, but not a meaningful metric scale
- Also known as an “ordinal utility function”
- Sometimes, only relative judgments (value functions) are necessary
- At other times, absolute judgments (utility functions) are required



# Money Versus Utility

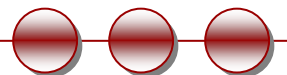
- Money  $\leftrightarrow$  Utility
  - More money is better, but not always in a linear relationship to the amount of money
- Expected Monetary Value
  - TV game show: you have won \$1,000,000
  - Take it or Gamble (flip coin to get \$2,500,000)
  - $EMV = .5(\$0) + .5(2,500,000) = 1,250,000$
  - $1,250,000 > 1,000,000$ : rational agent should take it right?
  - Assign utilities (might be different for average people and billionaires)





# Money Versus Utility

- Money  $\leftrightarrow$  Utility
  - More money is better, but not always in a linear relationship to the amount of money
- Expected Monetary Value
- Risk-averse:  $U(L) < U(S_{EMV(L)})$
- Risk-seeking:  $U(L) > U(S_{EMV(L)})$
- Risk-neutral:  $U(L) = U(S_{EMV(L)})$

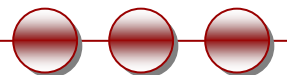






# Multiattribute Utility Theory

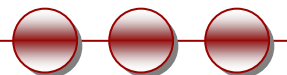
- A given state may have multiple utilities
  - ...because of multiple evaluation criteria
  - ...because of multiple agents (interested parties) with different utility functions
- We will talk about this more later in the semester, when we discuss multi-agent systems and game theory



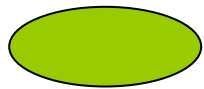


# Decision Networks

- Extend BNs to handle **actions** and **utilities**
- Also called *influence diagrams*
- Use BN inference methods to solve
- Perform *Value of Information* calculations



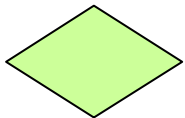
# Decision Networks cont.



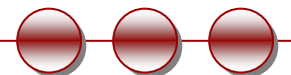
- Chance nodes: random variables, as in BNs



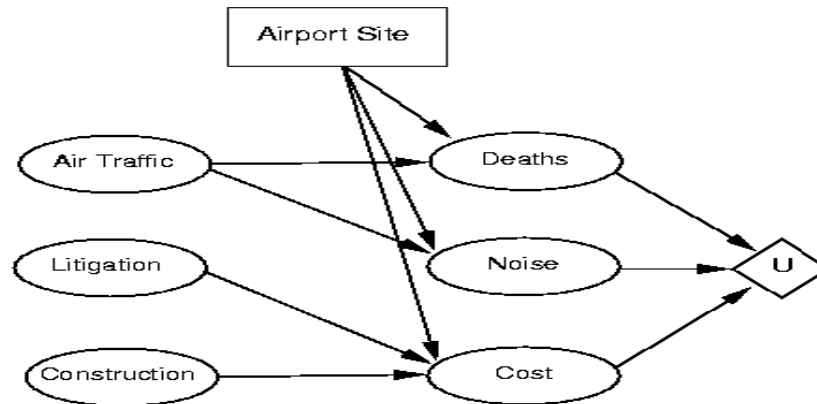
- Decision nodes: actions that a decision maker can take



- Utility/value nodes: the utility of an outcome state

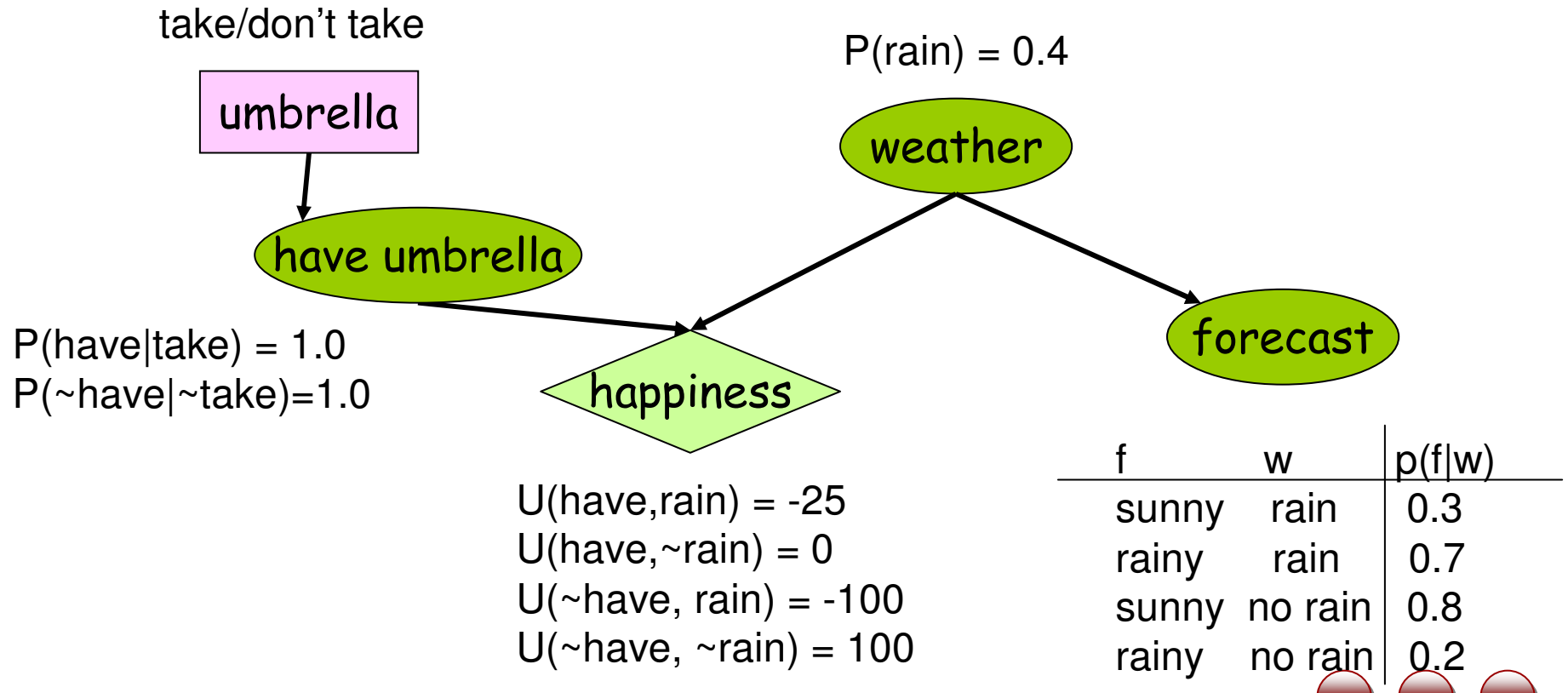
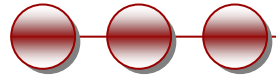


# R&N example



- Siting a new airport requires consideration of the disruption caused by construction; the cost of land; the distance from centers of population; the noise of flight operations; safety issues arising from local topography; weather conditions; and so on.

# Umbrella Network



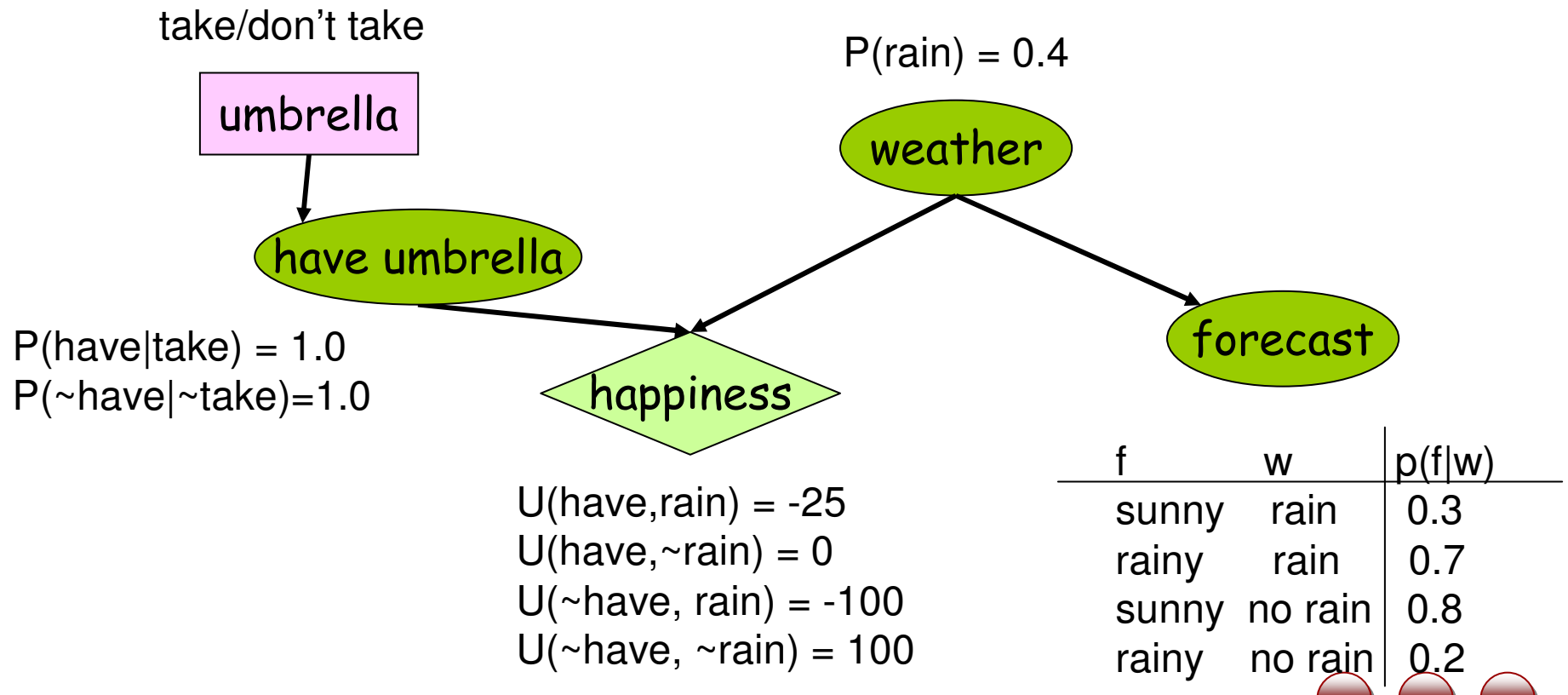
# Evaluating Decision Networks

- Set the evidence variables for current state
- For each possible value of the decision node:
  - Set decision node to that value
  - Calculate the posterior probability of the parent nodes of the utility node, using BN inference
  - Calculate the resulting utility for each action
- Return the action with the highest utility



# Decision Making: Umbrella Network

*Should I take my umbrella??*



# Value of Information (VOI)

- Suppose an agent's current knowledge is  $e$ . The value of the current best action  $\alpha$  is (slide 4):

$$EU(\alpha|e) = \max_a \sum_s P(\text{Result}(a)=s'|a,e)U(s')$$

- The value of the new best action after new evidence  $e'$  is obtained ( $E'=e'$ ):

$$EU(\alpha'|e,e') = \max_a \sum_s P(\text{Result}(a)=s'|a,e,e')U(s')$$

- The value of information for  $E'$  is therefore:

$$VOI(E') = \sum_k P(e_k | e)EU(\alpha_{e_k} | e_k, e) - EU(\alpha | e)$$



# Value of Information: Umbrella Network

*What is the value of knowing the weather forecast?*

