

Introduction

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Procedural shading is a proven rendering technique in which a short user-written procedure, called a *shader*, determines the shading and color variations across each surface. This gives great flexibility and control over the surface appearance.

The widest use of procedural shading is for production animation, where has been effectively used for years in commercials and feature films. These animations are rendered in software, taking from seconds to hours per frame. The resulting frames are typically replayed at 24-30 frames per second.

One important factor in procedural shading is the use of a shading language. A shading language is a high-level special-purpose language for writing shaders. The shading language provides a simple interface for the user to write new shaders. Pixar's RenderMan shading language [Upstill90] is the most popular, and several off-line renderers use it. A shader written in the RenderMan shading language can be used with any of these renderers.

Meanwhile, polygon-per-second performance has been the major focus for most *interactive* graphics hardware development. Only in the last few years has attention been given to surface shading quality for interactive graphics. Recently, great progress has been made on two fronts toward achieving real-time procedural shading. This course will cover progress on both. First, graphics hardware is capable of performing more of the computations necessary for shading. Second, new languages and *machine abstractions* have been developed that are better adapted for real-time use.

Interactive graphics machines are complex systems with relatively limited lifetimes. Just as the RenderMan shading language insulates the shading writer from the implementation details of the off-line renderer, a real-time shading system presents a simplified view of the interactive graphics hardware. This is done in two ways. First, we create an abstract model of the hardware. This abstract model gives the user a consistent high-level view of the graphics process that can be mapped onto the machine. Second, a special-purpose language allows a high-level description of each procedure. Given current hardware limitations, languages for real-time shading differ quite a bit from the one presented by RenderMan. Through these two, we can achieve *device-independence*, so procedures written for one graphics machine have the potential to work on other machines or other generations of the same machine.

1. Procedural techniques

Procedural techniques have been used in all facets of computer graphics, but most commonly for surface shading. As mentioned above, the job of a surface shading procedure is to choose a color for each pixel on a surface, incorporating any variations in color of the surface itself and the effects of lights that shine on the surface. A simple example may help clarify this.

We will show a shader that might be used for a brick wall (Figure 1.1). The wall is to be described as a single polygon with *texture coordinates*. These texture coordinates are not going to be used for image texturing: they are just a pair of numbers that parameterize the position on the surface.

The shader requires several additional parameters to describe the size, shape and color of the brick. These

are the width and height of the brick, the width of the mortar between bricks, and the colors for the mortar and brick (see Figure 1.1). These parameters are used to fold the texture coordinates into *brick coordinates* for each brick. These are (0,0) at one corner of each brick, and can be used to easily tell whether to use brick or mortar color. A portion of the brick shader is shown in Figure 1.2 (this shader happens to be written in the *pfman* language, detailed in Chapter 3). In this figure, *ss* and *tt* are local variables used to construct the brick coordinates. The simple bricks that result are shown in Figure 1.3a.

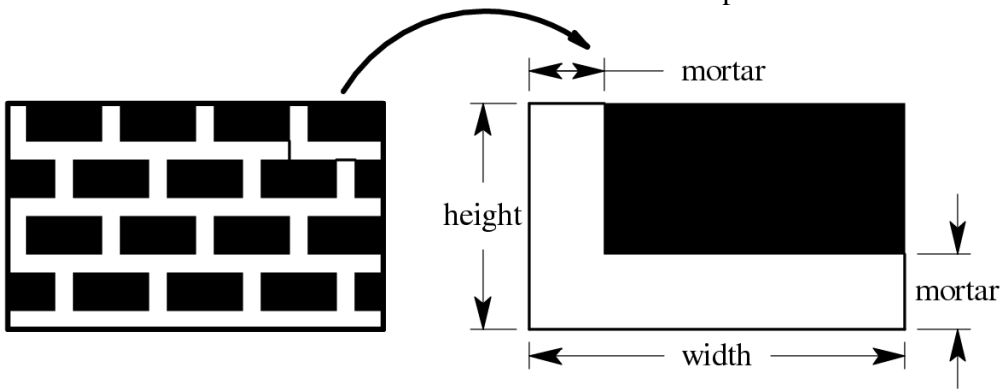


Figure 1.1. Size and shape parameters for brick shader

```
// find row of bricks for this pixel (row is 8-bit integer)
fixed<8,0> row = tt/height;

// offset even rows by half a row
if (row % 2 == 0) ss += width/2;

// wrap texture coordinates to get "brick coordinates"
ss = ss % width;
tt = tt % height;

// pick a color for this pixel, brick or mortar
float surface_color[3] = brick_color;
if (ss < mortar || tt < mortar)
    surface_color = mortar_color;
```

Figure 1.2. Portion of code for a simple brick shader

One of the real advantages of procedural shading is the ease with which shaders can be altered to produce the desired results. Figure 1.3 shows a series of changes from the simple brick shader to a much more realistic brick. Several of these changes demonstrate one of the most common features of procedural shaders: controlled randomness. With controlled use of random elements in the procedure, this same shader can be used for large or small walls without any two bricks looking the same. In contrast, an image texture would have to be re-rendered, re-scanned, or re-painted to handle a larger wall than originally intended.

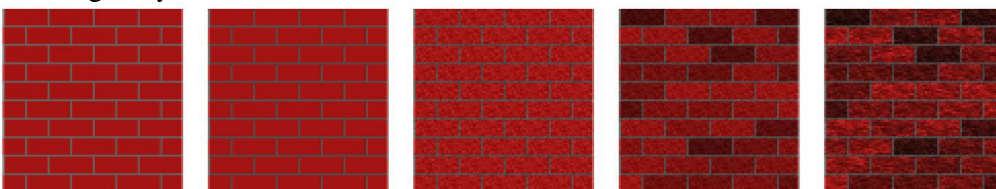


Figure 1.3. Evolution of a brick shader. a) simple version. b) with indented mortar. c) with added graininess. d) with variations in color from brick to brick. e) with color variations within each brick.

Procedural shading can also be used to create shaders that change with time or distance. Figure 1.4a and b are frames from a rippling mirror animated shader. Figure 1.4c shows a yellow brick road where

high-frequency elements fade out with distance. Figure 1.4d and e show a wood shader that uses surface position instead of texture coordinates. Figure 1.4d is also lit by a procedural light, simulating light shining through a paned window.

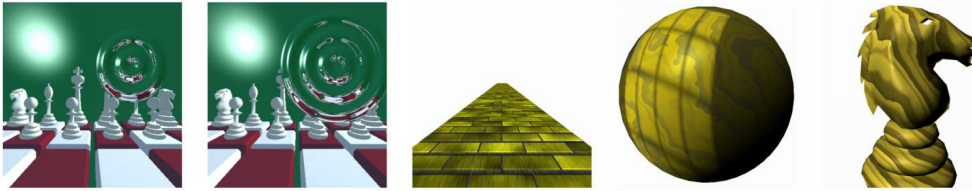


Figure 1.4. Examples of shaders. a+b) two frames of rippling mirror. c) yellow brick road. d+e) wood volume shader.

2. What's to come

These notes are divided into fifteen chapters, following a rough progression from the past of procedural shading, through present-day systems and on to research that may illuminate the future. We provide the following as a rough guide to the connection between chapters in these notes, the course presenters, and what you might expect to find there:

Chapter 1 (Marc Olano):	This introduction.
Chapter 2 (Ken Perlin):	Background on the beginnings of procedural shading and how (even then) it was influenced by hardware concerns.
Chapter 3 (Marc Olano):	The shading capabilities of PixelFlow, the first real-time shading system.
Chapter 4 (Wolfgang Heidrich):	Some issues that make evaluating shading expressions into a texture, one of the most common techniques for real-time shading, harder than it looks.
Chapter 5 (Wolfgang Heidrich):	Hardware shading effects, the building blocks for later procedural shading systems.
Chapter 6 (Marc Olano):	Multiple rendering passes using the building blocks from Chapter 5 can be put together to create a full-fledged real-time shading system
Chapter 7 (Erik Lindholm):	Vertex and texture shaders, some of the latest developments in making graphics hardware more flexible and programmable.
Chapter 8 (Bill Mark):	A shading language compiler that gives the same high-level interface for both multi-pass shading as introduced in Chapter 6 and shading hardware extensions as introduced in Chapter 7.
Chapter 9 (Ken Perlin):	Noise, one of the basic building blocks for procedural shading, and how it might be implemented efficiently.
Chapter 10 (John Hart):	Several methods for producing solid textures on hardware.
Chapter 11 (Marc Olano):	How multi-pass rendering techniques could be expanded to support a full-featured shading

language like RenderMan.

Chapter 12 (Michael McCool): A new graphics API built around a conceptual model of graphics hardware more appropriate for procedural shading.

Chapter 13 (Evan Hart): Though not course presenters, Evan Hart and Jason Mitchell have kindly provided details on ATI's new hardware shading extensions.

Chapter 14 (John Hart): A formal notation for analysis of different real-time shading techniques.

Chapter 15 (All): A collected bibliography of some of our favorite papers.